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of the one-dimensional polytropic ideal gas**

by

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ABSTRACT

In this paper the existence of the global solution of the outer pressure problem of the one-dimensional polytropic ideal gas is proved (Theorem 1). We shall also show that under some suitable assumptions the solution converges to a stationary state (Theorem 2).

1. Introduction.

We consider the one-dimensional motion of the polytropic ideal gas with inward pressed and adiabatic ends. Assuming that the reference configuration is the unit interval $[0,1]$, the motion is described by the following three equations in the Lagrangian coordinate corresponding to the law of mass, momentum and energy:

$$u_t = v_x, \quad (1.1)$$

$$v_t + R \left(\frac{\theta}{u} \right)_x = \mu \left(\frac{v_x}{u} \right)_x, \quad (1.2)$$

$$c_v \theta_t = -R \frac{\theta v_x}{u} + \mu \frac{v_x^2}{u} + \kappa \left(\frac{\theta_x}{u} \right)_x, \quad (1.3)$$

for $(x,t) \in [0,1] \times \mathbb{R}_+$ with the initial condition:

$$(u,v,\theta)(x,0) = (u_0,v_0,\theta_0)(x), \quad (1.4)$$

and the boundary conditions:

$$\left(-R \frac{\theta}{u} + \mu \frac{v_x}{u} \right)(0,t) = \left(-R \frac{\theta}{u} + \mu \frac{v_x}{u} \right)(1,t) = -P(t) < 0, \quad (1.5)$$

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$$\theta_x(0,t) = \theta_x(1,t) = 0, \quad (1.6)$$

where the unknown functions (u,v,θ) are the specific volume, the velocity and the absolute temperature respectively, the given function $P(t)$ is the outer pressure, and the positive constants R , μ , c_V and κ are the gas constant, the coefficient of viscosity, the heat capacity at constant volume and the coefficient of heat conduction respectively. The suffix t or x denotes the partial differentiation with respect to the variable t or x .

For physical reasons, we assume

$$u_0 > 0, \quad \theta_0 > 0. \quad (1.7)$$

Assume v is the velocity of the smooth solution. Integrating (1.2) over $[0,1] \times [0,t]$ by use of (1.5), we have

$$\int_0^1 v \, dx = \int_0^1 v_0 \, dx.$$

Since (1.1) - (1.3) are invariant with respect to adding any constant to v , without loss of generality, we may assume

$$\int_0^1 v_0 \, dx = 0. \quad (1.8)$$

Hence we have

$$\int_0^1 v \, dx = 0. \quad (1.9)$$

The local existence and the uniqueness of the solution of the outer pressure problem is established by Tani [9], [10] and Secchi-Valli [8] in the three-dimensional case. And in the one-dimensional case results on temporally global existence problem for the polytropic ideal gas with other boundary conditions are obtained by Kazhikhov [2], [3], Kazhikhov-Shelukhin [4] and Nagasawa [6] etc..

In this paper the global existence of solution for the problem (1.1) - (1.6) is established (Theorem 1), and the asymptotic behavior is studied under some suitable assumptions (Theorem 2). Roughly speaking, if $P(t)$ has a positive limit $\bar{P} > 0$ as $t \rightarrow +\infty$, then the solution (u,v,θ) converges to a stationary state $(\bar{u}, 0, \bar{\theta})$ in $W^{1,2}(0,1)$ as $t \rightarrow +\infty$, and the inner pressure $R \frac{\bar{\theta}}{\bar{u}}$ and the outer pressure P balance each other, i.e.,

$$R \frac{\bar{\theta}}{\bar{u}} = \lim_{t \rightarrow +\infty} R \frac{\theta}{u} = \lim_{t \rightarrow +\infty} P(t) = \bar{P}. \quad (1.10)$$

The convergence of the non-stationary solution to a stationary state was established in [3] in the

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case that the boundary condition (1.5) is replaced by

$$v(0,t) = v(1,t) = 0.$$

In this case, constants \bar{u} , $\bar{\theta}$ are determined by the initial value and the parameters of equations and $(\bar{u}, 0, \bar{\theta})$ is a stationary solution of the problem. In our case, however except the case of $P'(t) = 0$, \bar{u} , $\bar{\theta}$ is not determined by them (see (2.3) and (2.4)) and $(\bar{u}, 0, \bar{\theta})$ is not a stationary solution.

Unfortunately for technical reasons, we must assume that $P(t)$ is positive-valued and $\bar{P} > 0$. From the physical point of view, $P(t)$ is a non-negative-valued function. The author showed in [6] that in the case of $P(t) = 0$, the specific volume u is satisfied

$$u(x,t) \geq C(\log(1+t))^k$$

for some constants $C > 0$, $k \geq 1$ which are determined by the initial value and the parameters of equations. Therefore in this case any global solution (u, v, θ) does not converge to a stationary state as $t \rightarrow +\infty$. (The global existence in this case was proved in [2] and [4].)

2. Main results.

For function spaces $H^{n+\alpha}$, $H_T^{n+\alpha}$ and $B_T^{n+\alpha}$ we should refer to [6, Eq. (2.2) - (2.6)]. And other spaces $W^{1,2}(0,1)$ etc. are commonly used ones.

Throughout this paper we assume that the compatibility conditions are valid if they are not written down explicitly.

We will establish the following theorems:

Theorem 1. *If the initial and boundary data satisfying (1.7) and (1.8) belong to $u_0 \in H^{1+\alpha}$, $v_0 \in H^{2+\alpha}$, $\theta_0 \in H^{2+\alpha}$ for some $\alpha \in (0,1)$, and $P(t) \in C^1$, then there exists a temporally global and unique solution for the problem (1.1) - (1.6) such that this solution (u, v, θ) belongs to $B_T^{1+\alpha} \times H_T^{2+\alpha} \times H_T^{2+\alpha}$ and has generalized derivatives u_{xt} , v_{xt} , $\theta_{xt} \in L^2((0,1) \times (0,T))$ for any $T \in (0, +\infty)$. Moreover $u > 0$ and $\theta > 0$.*

Theorem 2. *Assume that the hypotheses of Theorem 1 hold, and that $P(t)$ satisfies*

$$m_P = \inf_{t \in [0, +\infty)} P(t) > 0, \quad (2.1)$$

$$TV(P) = \int_0^{+\infty} |P'(t)| dt < +\infty. \quad (2.2)$$

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Then the limits

$$\bar{P} = \lim_{t \rightarrow +\infty} P(t) (> 0) \text{ and } \lim_{t \rightarrow +\infty} \int_0^t P'(\tau) \int_0^1 u(x, \tau) dx d\tau$$

exist, and the solution (u, v, θ) converges to a stationary state $(\bar{u}, 0, \bar{\theta})$ in $W^{1,2}(0,1) \cap C[0,1]$ as $t \rightarrow +\infty$, where $\bar{u}, \bar{\theta}$ are positive constants given by

$$\bar{u} = \frac{R}{\bar{P}(c_v + R)} \left\{ \int_0^1 \left(\frac{1}{2} v_0^2 + c_v \theta_0 + P(0) u_0 \right) dx + \int_0^{+\infty} P'(\tau) \int_0^1 u(x, \tau) dx d\tau \right\}, \quad (2.3)$$

$$\bar{\theta} = \frac{1}{c_v + R} \left\{ \int_0^1 \left(\frac{1}{2} v_0^2 + c_v \theta_0 + P(0) u_0 \right) dx + \int_0^{+\infty} P'(\tau) \int_0^1 u(x, \tau) dx d\tau \right\}. \quad (2.4)$$

Thus \bar{u} and $\bar{\theta}$ satisfy (1.10).

Remark. The constant state $(\bar{u}, 0, \bar{\theta})$ is a stationary solution of (1.1) - (1.6) with $P(t) = \bar{P}$.

3. Global existence (a priori estimates).

The proof of Theorem 1 is based on the local existence theorem and on the a priori estimates. However the problem is the one-dimensional case of [9], so the local existence theorem can be established in the similar method. For details, we should refer to [9].

Therefore we investigate the a priori estimates of the solution (u, v, θ) such as

$$\|u(\cdot, t)\|^{(1+\alpha)} + \|v(\cdot, t)\|^{(2+\alpha)} + \|\theta(\cdot, t)\|^{(2+\alpha)} \leq C(t), \quad (3.1)$$

$$\min \left\{ \min_{x \in [0,1]} u(x, t), \min_{x \in [0,1]} \theta(x, t) \right\} \geq C^{-1}(t). \quad (3.2)$$

From now on, $C, C(\cdot), C(\cdot, \cdot)$ etc. denote positive constants depending on (their argument(s) and) possibly the initial value and parameters of equations. For convenience we sometimes denote different constants by the same symbol C even in the same sentence. When different constants should be distinguished, we use the numbered symbol C_i .

Here we introduce the useful abbreviations as follows:

$$\begin{cases} m_u(t) = \min_{x \in [0,1]} u(x, t), M_u(t) = \max_{x \in [0,1]} u(x, t), \\ m_\theta(t) = \min_{x \in [0,1]} \theta(x, t), M_\theta(t) = \max_{x \in [0,1]} \theta(x, t). \end{cases}$$

In proving (3.1) and (3.2), we need several lemmas concerning the estimates of the solution and its derivatives.

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In order to get the estimate (3.2), we proceed the argument under the assumption that $u > 0, \theta > 0$.

Remark. $\theta > 0$ is a consequence of $u > 0$. Indeed we apply the maximum principle [7] to (1.3). In consequence of (1.7), we conclude that

$$\begin{cases} \theta(x,t) \geq 0 & \text{on } [0,1] \times [0,+\infty), \\ \theta(x,t) > 0 & \text{on } (0,1) \times [0,+\infty). \end{cases}$$

If $\theta(0,t) = 0$ for some $t \in [0,+\infty)$, from the above inequalities and (1.6), $\theta_t(0,t) = 0$, $\theta_x(0,t) = 0$ and $\theta_{xx}(0,t) \geq 0$ hold. Therefore from (1.3),

$$\left(\mu \frac{v_x^2}{u} + \kappa \frac{\theta_{xx}}{u} \right)(0,t) = 0.$$

Hence it must be that

$$v_x(0,t) = \theta_{xx}(0,t) = 0.$$

But it is impossible because of (1.5). In the similar way, we get $\theta(1,t) > 0$.

Lemma 3.1. *We have*

$$\int_0^1 (v^2 + \theta + u) dx \leq C(t). \quad (3.3)$$

Proof. Integrating (1.1) over $[0,1]$, we obtain

$$\left(\int_0^1 u dx \right)_t = v(1,t) - v(0,t).$$

Multiplying both sides of (1.2) by v , adding them to (1.3), and integrating, we have

$$\begin{aligned} \left\{ \int_0^1 \left(\frac{1}{2} v^2 + c_v \theta \right) dx \right\}_t &= \left[-R \frac{\theta v}{u} + \mu \frac{v_x v}{u} + \kappa \frac{\theta_x}{u} \right]_{x=0}^{x=1} \\ &= -P(t)(v(1,t) - v(0,t)) \\ &= -P(t) \left(\int_0^1 u dx \right)_t. \end{aligned}$$

Therefore we have

$$\begin{aligned} &\int_0^1 \left(\frac{1}{2} v^2 + c_v \theta + P(t)u \right) dx \\ &= \int_0^1 \left(\frac{1}{2} v_0^2 + c_v \theta_0 + P(0)u_0 \right) dx + \int_0^t P'(\tau) \int_0^1 u(x,\tau) dx d\tau \\ &\leq C + \int_0^t |(\log P(\tau))'| \cdot P(\tau) \int_0^1 u(x,\tau) dx d\tau. \end{aligned} \quad (3.4)$$

Now we apply Gronwall's lemma, and then we get

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$$\int_0^1 \left(\frac{1}{2} v^2 + c_v \theta + P(t) u \right) dx \leq C(t).$$

Since $P(t) > 0$, we have

$$\int_0^1 u \, dx \leq C(t) P^{-1}(t) \leq \tilde{C}(t). \quad \square$$

Lemma 3.2. *We have*

$$U(t) + \int_0^t V(\tau) d\tau \leq C(t), \quad (3.5)$$

where

$$U(t) = \int_0^1 \left\{ \frac{1}{2} v^2 + R(u - \log u - 1) + c_v(\theta - \log \theta - 1) \right\} dx, \quad (3.6)$$

$$V(t) = \int_0^1 \left\{ \mu \frac{v_x^2}{u\theta} + \kappa \frac{\theta_x^2}{u\theta^2} \right\} dx. \quad (3.7)$$

Proof. From (1.1) - (1.3), (1.5) and (1.6), it is easy to show the following identity:

$$U'(t) + V(t) = (R - P(t)) \left(\int_0^1 u \, dx \right)_t.$$

Therefore, by Lemma 3.1, we have

$$\begin{aligned} U(t) + \int_0^t V(\tau) d\tau &= U(0) + R \int_0^1 (u - u_0) dx \\ &\quad - P(t) \int_0^1 u \, dx + P(0) \int_0^1 u_0 dx + \int_0^t P'(\tau) \int_0^1 u(x, \tau) dx d\tau \leq C(t). \quad \square \end{aligned}$$

Lemma 3.3. *We have*

$$u(x, t) = \frac{1}{B(x, t) Y(t)} \left(u_0(x) + \int_0^t \frac{R}{\mu} \theta(x, \tau) B(x, \tau) Y(\tau) d\tau \right) \quad (3.8)$$

where

$$B(x, t) = \exp \left\{ \frac{1}{\mu} \int_0^x (v_0(\xi) - v(\xi, t)) d\xi \right\}, \quad (3.9)$$

$$Y(t) = \exp \left\{ \frac{1}{\mu} \int_0^t P(\tau) d\tau \right\}. \quad (3.10)$$

Proof. Integrating (1.2) over $[0, x] \times [0, t]$, and taking exponent, we get

$$\frac{1}{u(x, t)} \exp \left(\frac{R}{\mu} \int_0^t \frac{\theta(x, \tau)}{u(x, \tau)} d\tau \right) = \frac{1}{u_0(x)} B(x, t) Y(t).$$

To calculate the exponent part of the left-hand side, we multiply by $\frac{R}{\mu} \theta$, and integrate in t . Thus,

we have

$$\exp \left(\frac{R}{\mu} \int_0^t \frac{\theta}{u} d\tau \right) = 1 + \frac{1}{u_0} \int_0^t \frac{R}{\mu} \theta \cdot B \cdot Y \, d\tau. \quad \square$$

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Lemma 3.4. *We have*

$$M_\theta(t) \leq C(t)(1 + M_u(t)V(t)), \quad (3.11)$$

$$m_\theta(t) \geq C^{-1} \left(1 + \int_0^t \frac{d\tau}{m_u(\tau)} \right)^{-1}. \quad (3.12)$$

Proof. For any $t \geq 0$, there exists $y(t) \in [0,1]$ such that

$$\theta(y(t), t) = \int_0^1 \theta \, dx.$$

Therefore we have

$$\begin{aligned} \theta^{\frac{1}{2}}(x, t) &= \theta^{\frac{1}{2}}(y(t), t) + \int_{y(t)}^x \frac{\theta_x(\xi, t)}{2\theta^{\frac{1}{2}}(\xi, t)} d\xi \\ &\leq \left(\int_0^1 \theta \, dx \right)^{\frac{1}{2}} \left\{ 1 + \frac{1}{2} \left(M_u(t) \int_0^1 \frac{\theta_x^2}{u\theta^2} dx \right)^{\frac{1}{2}} \right\}. \end{aligned}$$

Using Lemma 3.1, we obtain (3.11).

Setting $\theta^{-1} = \omega$, we rewrite (1.3) as follows:

$$\begin{aligned} c_V \omega_t &= \kappa \left(\frac{\omega_x}{u} \right)_x - \left\{ 2\kappa \frac{\theta}{u} \omega_x^2 + \frac{\mu}{u} \left(\omega v_x - \frac{R}{2\mu} \right)^2 \right\} + \frac{R^2}{4\mu u} \\ &\leq \kappa \left(\frac{\omega_x}{u} \right)_x + \frac{R^2}{4\mu u}. \end{aligned}$$

We multiply both sides by $2r\omega^{2r-1}$ ($r > \frac{1}{2}$), and integrate over $[0,1]$. Since $\omega_x = 0$ at $x = 0$ and 1 , we get the following estimate through the integration by parts and Hölder's inequality,

$$\begin{aligned} 2c_V r \left(\int_0^1 \omega^{2r} dx \right)^{1-\frac{1}{2r}} &\left\{ \left(\int_0^1 \omega^{2r} dx \right)^{\frac{1}{2r}} \right\}, \\ &\leq -\kappa \int_0^1 2r(2r-1)\omega^{2r-2} \frac{\omega_x^2}{u} dx + 2c_V r \left(\int_0^1 \omega^{2r} dx \right)^{1-\frac{1}{2r}} \cdot \frac{R^2}{4\mu c_V} \left\{ \int_0^1 \left(\frac{1}{u} \right)^{2r} dx \right\}^{\frac{1}{2r}}. \end{aligned}$$

Majorizing the first term of the right-hand side by zero, dividing both sides by $2c_V r \left(\int_0^1 \omega^{2r} dx \right)^{1-\frac{1}{2r}}$, and integrating over $[0, t]$, we have

$$\left(\int_0^1 \omega^{2r} dx \right)^{\frac{1}{2r}} \leq C \left(1 + \int_0^t \frac{d\tau}{m_u(\tau)} \right).$$

Putting $r \rightarrow \infty$, we get (3.12). \square

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Lemma 3.5. *We have*

$$M_u(t) + \int_0^t M_\theta(\tau) d\tau \leq C(t), \quad (3.13)$$

$$m_u(t), m_\theta(t) \geq C^{-1}(t). \quad (3.14)$$

Proof. From the assumption on $P(t)$, and Lemma 3.1, we have

$$0 < C^{-1}(t) \leq B(x, t), Y(t) \leq C(t).$$

Therefore, using (3.8), (3.11) and (3.12), we have (3.14) and the estimate

$$M_u(t) \leq C(t) \left(1 + \int_0^t M_u(\tau) V(\tau) d\tau \right).$$

Taking into account of (3.5), we get

$$M_u(t) \leq C(t)$$

by Gronwall's lemma. Using (3.11) and (3.5), we have

$$\int_0^t M_\theta(\tau) d\tau \leq C(t). \quad \square$$

Lemma 3.6. *We have*

$$\int_0^1 (v^4 + \theta^2) dx + \int_0^t \int_0^1 (\theta_x^2 + v^2 v_x^2) dx d\tau \leq C(t). \quad (3.15)$$

Proof. Setting $w = \frac{1}{2}v^2 + c_v\theta$, we rewrite (1.2) and (1.3) in the following form:

$$w_t = \left(-R \frac{\theta v}{u} + \mu \frac{v v_x}{u} + \kappa \frac{\theta_x}{u} \right)_x.$$

Multiplying both sides by w , and integrating over $[0, 1]$, we have

$$\begin{aligned} & \left(\int_0^1 \frac{1}{2} w^2 dx \right)_t + \kappa c_v \int_0^1 \frac{\theta_x^2}{u} dx \\ &= \int_0^1 \left\{ \left(R \frac{\theta v}{u} - \mu \frac{v v_x}{u} \right) (v v_x + c_v \theta_x) - \kappa \frac{\theta_x v v_x}{u} \right\} dx \\ & \quad - P(t) \left\{ v(1, t) \left(\frac{1}{2} v^2(1, t) + c_v \theta(1, t) \right) - v(0, t) \left(\frac{1}{2} v^2(0, t) + c_v \theta(0, t) \right) \right\} \\ &\leq \frac{\kappa c_v}{2} \int_0^1 \frac{\theta_x^2}{u} dx + C \int_0^1 \left(\frac{\theta^2 v^2}{u} + \frac{v^2 v_x^2}{u} \right) dx \\ & \quad + CP(t) (|v^3(1, t)| + |v^3(0, t)| + |v(1, t)\theta(1, t)| + |v(0, t)\theta(0, t)|). \end{aligned}$$

Taking into account of (1.9), $|v^3|$ can be majorized as follows:

$$|v^3| \leq 3 \int_0^1 v^2 |v_x| dx \leq \left(\epsilon \int_0^1 v^2 v_x^2 dx + C(\epsilon) \int_0^1 v^2 dx \right) \quad (3.16)$$

for any $\epsilon > 0$. From (3.13), (3.3) and (3.7), we have

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$$|v| \leq \int_0^1 |v_x| dx \leq \left(\int_0^1 \frac{u \theta}{\mu} dx \right)^{\frac{1}{2}} \left(\int_0^1 \mu \frac{v_x^2}{u \theta} dx \right)^{\frac{1}{2}} \leq C(t) V^{\frac{1}{2}}(t), \quad (3.17)$$

$$\theta \leq \int_0^1 \theta dx + \int_0^1 |\theta_x| dx \leq C(t) + \left(\int_0^1 \theta_x^2 dx \right)^{\frac{1}{2}}.$$

Therefore we have

$$|v \theta| \leq C(t) V^{\frac{1}{2}}(t) + \epsilon \int_0^1 \theta_x^2 dx + C(\epsilon, t) V(t)$$

for any $\epsilon > 0$. Taking ϵ sufficiently small, we have

$$\left(\int_0^1 w^2 dx \right)_t + \int_0^1 \theta_x^2 dx \leq C(t) \left\{ 1 + V(t) + \int_0^1 \left(\frac{\theta^2 v^2}{u} + \frac{v^2 v_x^2}{u} \right) dx \right\}. \quad (3.18)$$

Here we use (3.13). Multiplying (1.2) by v^3 , and integrating over $[0,1]$, we have

$$\begin{aligned} \left(\int_0^1 \frac{1}{4} v^4 dx \right)_t &= -P(t) \{v^3(1,t) - v^3(0,t)\} + 3 \int_0^1 \left(R \frac{\theta}{u} - \mu \frac{v_x}{u} \right) v^2 v_x dx \\ &\leq C(t) \left(V(t) + \int_0^1 \frac{\theta^2 v^2}{u} dx \right) - 2\mu \int_0^1 \frac{v_x^2 v^2}{u} dx. \end{aligned} \quad (3.19)$$

Here we use (3.16) with ϵ sufficiently small and (3.17). From this estimate (3.18) and (3.17), we get

$$\begin{aligned} \int_0^1 (v^4 + \theta^2) dx + \int_0^t \int_0^1 (\theta_x^2 + v_x^2 v^2) dx d\tau &\leq C(t) \left(1 + \int_0^t \max_{x \in [0,1]} v^2(x, \tau) \int_0^1 \theta^2 dx \right) \\ &\leq C(t) \left(1 + \int_0^t V(\tau) \int_0^1 \theta^2 dx d\tau \right). \end{aligned}$$

Applying Gronwall's lemma, we get (3.15). \square

Lemma 3.7. *We have*

$$\int_0^1 u_x^2 dx \leq C(t). \quad (3.20)$$

Proof. Differentiating (3.8) with respect to x , we get an expression of u_x . From it, we have

$$\int_0^1 u_x^2 dx \leq C(t) \left[\int_0^1 v^2 dx + 1 + \int_0^t \left\{ \int_0^1 \theta_x^2 dx + M_\theta \int_0^1 \theta(1 + v^2) dx \right\} d\tau \right] \leq C(t). \quad \square$$

Lemma 3.8. *We have*

$$\int_0^t \int_0^1 v_x^2 dx d\tau \leq C(t). \quad (3.21)$$

Proof. Multiplying (1.2) by v , and integrating over $[0,1]$, we have

$$\begin{aligned} \left(\int_0^1 \frac{1}{2} v^2 dx \right)_t + P(t) \left(\int_0^1 u dx \right)_t + \mu \int_0^1 \frac{v_x^2}{u} dx \\ = R \int_0^1 \frac{\theta v_x}{u} dx \leq \frac{\mu}{2} \int_0^1 \frac{v_x^2}{u} dx + C \int_0^1 \frac{\theta^2}{u} dx. \end{aligned}$$

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Therefore, we have

$$\begin{aligned} & \int_0^1 \frac{1}{2} v^2 dx + P(t) \int_0^1 u dx + \frac{\mu}{2} \int_0^t \int_0^1 \frac{v_x^2}{u} dx \\ & \leq \int_0^1 \frac{1}{2} v_0^2 dx + P(0) \int_0^1 u_0 dx + \int_0^t |P'(\tau)| \int_0^1 u dx d\tau + C \int_0^t \int_0^1 \frac{\theta^2}{u} dx d\tau \\ & \leq C(t), \end{aligned}$$

from (3.3) and (3.13) - (3.15). \square

Lemma 3.9. *We have*

$$\int_0^1 v_x^2 dx + \int_0^t \int_0^1 v_{xx}^2 dx d\tau \leq C(t) \left[1 + \left\{ \int_0^t v_i^2(0, \tau) d\tau \right\}^{\frac{1}{2}} + \left\{ \int_0^t v_i^2(1, \tau) d\tau \right\}^{\frac{1}{2}} \right]. \quad (3.22)$$

Proof. Multiplying (1.2) by v_{xx} , and integrating over $[0, 1]$, we have

$$\begin{aligned} & \left(\int_0^1 \frac{1}{2} v_x^2 dx \right)_t + \int_0^1 \mu \frac{v_{xx}^2}{u} dx \\ & = \int_0^1 \left(R \frac{\theta_x v_{xx}}{u} - R \frac{u_x \theta v_{xx}}{u^2} + \mu \frac{v_x u_x v_{xx}}{u^2} \right) dx + v_x(1, t) v_t(1, t) - v_x(0, t) v_t(0, t) \\ & \leq \int_0^1 \frac{\mu}{2} \frac{v_{xx}^2}{u} dx + C(t) \left[\int_0^1 \theta_x^2 dx + \left(M_\theta^2(t) + \max_{x \in [0, 1]} v_x^2 \right) \int_0^1 u_x^2 dx \right] \\ & \quad + v_x(1, t) v_t(1, t) - v_x(0, t) v_t(0, t). \end{aligned} \quad (3.23)$$

From (3.15), we have

$$\int_0^t M_\theta^2(\tau) d\tau \leq \int_0^t \left(\int_0^1 \theta^2 dx + \int_0^1 2\theta |\theta_x| dx \right) d\tau \leq C \int_0^t \int_0^1 (\theta^2 + \theta_x^2) dx d\tau \leq C(t). \quad (3.24)$$

Integrating (3.23) over $[0, t]$, we get

$$\begin{aligned} & \int_0^1 v_x^2 dx + \int_0^t \int_0^1 v_{xx}^2 dx d\tau \leq C(t) \left[1 + \int_0^t \max_{x \in [0, 1]} v_x^2(x, \tau) d\tau \right. \\ & \quad \left. + \left\{ \int_0^t v_i^2(1, \tau) d\tau \int_0^t v_x^2(1, \tau) d\tau \right\}^{\frac{1}{2}} + \left\{ \int_0^t v_i^2(0, \tau) d\tau \int_0^t v_x^2(0, \tau) d\tau \right\}^{\frac{1}{2}} \right], \end{aligned} \quad (3.25)$$

from (3.20) and (3.24). We must evaluate the right-hand side of (3.25). From (3.21), we have

$$\begin{aligned} & \int_0^t \max_{x \in [0, 1]} v_x^2(x, \tau) d\tau \leq \int_0^t \left\{ \int_0^1 v_x^2 dx + \int_0^1 2|v_x v_{xx}| dx \right\} d\tau \\ & \leq \epsilon \int_0^t \int_0^1 v_{xx}^2 dx d\tau + C(\epsilon) \int_0^t \int_0^1 v_x^2 dx d\tau \\ & \leq \epsilon \int_0^t \int_0^1 v_{xx}^2 dx d\tau + C(\epsilon, t). \end{aligned} \quad (3.26)$$

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From (1.5), we have

$$\int_0^t v_x^2(1, \tau) d\tau \leq C \int_0^t (P^2(\tau) M_u^2(\tau) + M_\theta^2(\tau)) d\tau \leq C(t). \quad (3.27)$$

In the same way, we have

$$\int_0^t v_x^2(0, \tau) d\tau \leq C(t). \quad (3.28)$$

From (3.25), (3.26) with sufficiently small ϵ , and (3.27) - (3.28), we get the assertion. \square

Lemma 3.10. For any $\epsilon > 0$, we have

$$\int_0^1 \theta_x^2 dx + \int_0^t \int_0^1 \theta_{xx}^2 dx d\tau \leq \epsilon \int_0^t (v_t^2(1, \tau) + v_t^2(0, \tau)) d\tau + C(\epsilon, t). \quad (3.29)$$

Proof. Multiplying (1.3) by θ_{xx} , and integrating over $[0, 1]$, we have

$$\begin{aligned} & \left\{ \int_0^1 \frac{c_V}{2} \theta_x^2 dx \right\}_t + \int_0^1 \kappa \frac{\theta_{xx}^2}{u} dx \\ &= \int_0^1 \left(R \frac{\theta v_x \theta_{xx}}{u} - \mu \frac{v_x^2 \theta_{xx}}{u} + \kappa \frac{u_x \theta_x \theta_{xx}}{u^2} \right) dx \\ &\leq \int_0^1 \frac{\kappa}{2} \frac{\theta_{xx}^2}{u} dx + C(t) \left\{ \max_{x \in [0, 1]} v_x^2(x, t) \int_0^1 (\theta^2 + v_x^2) dx + \max_{x \in [0, 1]} \theta_x^2 \int_0^1 u_x^2 dx \right\}. \end{aligned}$$

Therefore, we have

$$\begin{aligned} & \int_0^1 \theta_x^2 dx + \int_0^t \int_0^1 \theta_{xx}^2 dx d\tau \\ &\leq C(t) \left[1 + \int_0^t \left\{ \max_{x \in [0, 1]} v_x^2(x, \tau) \left(1 + \int_0^1 v_x^2 dx \right) + \max_{x \in [0, 1]} \theta_x^2(x, \tau) \right\} d\tau \right]. \end{aligned} \quad (3.30)$$

Here we use (3.15) and (3.20). From (3.22) and (3.26), we have

$$\int_0^t \max_{x \in [0, 1]} v_x^2 d\tau \leq \epsilon_1 \int_0^t (v_t^2(1, \tau) + v_t^2(0, \tau)) d\tau + C(\epsilon_1, t), \quad (3.31)$$

and

$$\begin{aligned} & \int_0^t \max_{x \in [0, 1]} v_x^2(x, \tau) \cdot \int_0^1 v_x^2(x, \tau) dx d\tau \\ &\leq \int_0^t \max_{x \in [0, 1]} v_x^2(x, \tau) d\tau \cdot \max_{\tau \in [0, t]} \int_0^1 v_x^2(x, \tau) dx \\ &\leq \left\{ \epsilon_2 \int_0^t \int_0^1 v_{xx}^2 dx d\tau + C(\epsilon_2, t) \right\} \\ &\quad \times C(t) \left[1 + \left\{ \int_0^t v_t^2(1, \tau) d\tau \right\}^{\frac{1}{2}} + \left\{ \int_0^t v_t^2(0, \tau) d\tau \right\}^{\frac{1}{2}} \right] \\ &\leq \epsilon_2 C(t) \left[1 + \left\{ \int_0^t v_t^2(1, \tau) d\tau \right\}^{\frac{1}{2}} + \left\{ \int_0^t v_t^2(0, \tau) d\tau \right\}^{\frac{1}{2}} \right]^2 \\ &\quad + C(\epsilon_2, t) \left[1 + \left\{ \int_0^t v_t^2(1, \tau) d\tau \right\}^{\frac{1}{2}} + \left\{ \int_0^t v_t^2(0, \tau) d\tau \right\}^{\frac{1}{2}} \right] \end{aligned}$$

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$$\leq \epsilon_3 \int_0^t (v_t^2(1, \tau) + v_t^2(0, \tau)) d\tau + C(\epsilon_3, t), \quad (3.32)$$

where

$$\epsilon_3 = \epsilon_2 C(t) + \text{any positive number.}$$

In the same way, from (1.6) and (3.15), we have

$$\begin{aligned} \int_0^t \max_{x \in [0,1]} \theta_x^2(x, \tau) d\tau &\leq \int_0^t \int_0^1 2|\theta_x \theta_{xx}| dx d\tau \\ &\leq \epsilon_4 \int_0^t \int_0^1 \theta_{xx}^2 dx d\tau + C(\epsilon_4) \int_0^t \int_0^1 \theta_x^2 dx d\tau \\ &\leq \epsilon_4 \int_0^t \int_0^1 \theta_{xx}^2 dx d\tau + C(\epsilon_4, t). \end{aligned} \quad (3.33)$$

Setting ϵ_j 's sufficiently small, we get (3.29) from (3.30) - (3.33). \square

Lemma 3.11. For any $\epsilon > 0$, we have

$$\int_0^t \int_0^1 \theta_t^2 dx d\tau \leq \epsilon \int_0^t (v_t^2(1, \tau) + v_t^2(0, \tau)) d\tau + C(\epsilon, t). \quad (3.34)$$

Proof. From (1.3) and (3.14), we have

$$\begin{aligned} \int_0^t \int_0^1 \theta_t^2 dx d\tau &\leq C(t) \int_0^t \left\{ M_0^2(t) + \max_{x \in [0,1]} v_x^2(x, \tau) \right\} \int_0^1 v_x^2 dx \\ &\quad + \max_{x \in [0,1]} \theta_x^2(x, \tau) \int_0^1 u_x^2 dx + \int_0^1 \theta_{xx}^2 dx \Big\} d\tau. \end{aligned}$$

It yields (3.34) by use of (3.24), (3.32), (3.20), (3.33) and (3.29). \square

Lemma 3.12. The function $v(x, t)$ possesses a generalized derivative $v_{xt} \in L^2((0,1) \times (0, t))$, and we have

$$\int_0^1 v_t^2 dx + \int_0^t \int_0^1 v_{xt}^2 dx d\tau + \int_0^t (v_t^2(1, \tau) + v_t^2(0, \tau)) d\tau \leq C(t). \quad (3.35)$$

Proof. For a positive number Δt and a function $f(x, t)$,

$$\Delta f \stackrel{\text{def}}{=} f(x, t + \Delta t) - f(x, t).$$

From (1.2), we get

$$\left(\frac{\Delta v}{\Delta t} \right)_t = \left\{ \frac{\Delta \left(-R \frac{\theta}{u} + \mu \frac{v_x}{u} \right)}{\Delta t} \right\}_x.$$

Multiplying both sides by $\frac{\Delta v}{\Delta t}$, and integrating them over $[0,1]$, we get by the integration by parts with the boundary condition (1.5),

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$$\begin{aligned} \left\{ \frac{1}{2} \int_0^1 \left(\frac{\Delta v}{\Delta t} \right)^2 dx \right\}_t &= \left[- \frac{\Delta P}{\Delta t} \frac{\Delta v}{\Delta t} \right]_{x=0}^{x=1} \\ &+ \int_0^1 \left\{ R \frac{1}{u(x,t+\Delta t)} \frac{\Delta \theta}{\Delta t} \frac{\Delta v_x}{\Delta t} + R \theta(x,\tau) \frac{\Delta \left(\frac{1}{u} \right)}{\Delta t} \frac{\Delta v_x}{\Delta t} \right. \\ &\left. - \mu \frac{1}{u(x,t+\Delta t)} \left(\frac{\Delta v_x}{\Delta t} \right)^2 - \mu \frac{\Delta \left(\frac{1}{u} \right)}{\Delta t} v_x(x,\tau) \frac{\Delta v_x}{\Delta t} \right\} dx. \end{aligned}$$

We evaluate the first term of the right-hand side as follows:

$$\begin{aligned} \left| \frac{\Delta P}{\Delta t} \frac{\Delta v}{\Delta t} \right| &\leq \max_{\tau \in [t, t+\Delta t]} |P'(\tau)| \left(\left(\frac{\Delta v}{\Delta t} \right)^2 + 1 \right), \\ \left(\frac{\Delta v}{\Delta t} \right)^2 &\leq \int_0^1 \left\{ \left(\frac{\Delta v}{\Delta t} \right)^2 + 2 \left| \frac{\Delta v_x}{\Delta t} \right| \left| \frac{\Delta v}{\Delta t} \right| \right\} dx \\ &\leq \epsilon \int_0^1 \left(\frac{\Delta v_x}{\Delta t} \right)^2 dx + C(\epsilon) \int_0^1 \left(\frac{\Delta v}{\Delta t} \right)^2 dx. \end{aligned}$$

Therefore, we have

$$\begin{aligned} \left\{ \int_0^1 \left(\frac{\Delta v}{\Delta t} \right)^2 dx \right\}_t &+ \int_0^1 \left(\frac{\Delta v_x}{\Delta t} \right)^2 dx + \left(\frac{\Delta v}{\Delta t} \right)^2(1,t) + \left(\frac{\Delta v}{\Delta t} \right)^2(0,t) \\ &\leq C(t) \left[1 + \int_0^1 \left\{ \left(\frac{\Delta \theta}{\Delta t} \right)^2 + \left(\frac{\Delta \left(\frac{1}{u} \right)}{\Delta t} \right)^2 (\theta^2 + v_x^2) + \left(\frac{\Delta v}{\Delta t} \right)^2 \right\} dx \right]. \end{aligned}$$

Integrating over $[0, t]$, we get

$$\begin{aligned} \int_0^1 \left(\frac{\Delta v}{\Delta t} \right)^2 dx + \int_0^t \int_0^1 \left(\frac{\Delta v_x}{\Delta t} \right)^2 dx d\tau &+ \int_0^1 \left\{ \left(\frac{\Delta v}{\Delta t} \right)^2(1,\tau) + \left(\frac{\Delta v}{\Delta t} \right)^2(0,\tau) \right\} d\tau \\ &\leq C(t) \left[\int_0^1 \left(\frac{\Delta v}{\Delta t} \right)^2 dx \right]_{t=0} + 1 \\ &+ \int_0^t \int_0^1 \left\{ \left(\frac{\Delta \theta}{\Delta t} \right)^2 + \left(\frac{\Delta v}{\Delta t} \right)^2 + \left(\frac{\Delta \left(\frac{1}{u} \right)}{\Delta t} \right)^2 (\theta^2 + v_x^2) \right\} dx d\tau. \end{aligned}$$

By the application of Gronwall's lemma, we have

$$\int_0^t \left\{ \left(\frac{\Delta v}{\Delta t} \right)^2(1,\tau) + \left(\frac{\Delta v}{\Delta t} \right)^2(0,\tau) \right\} d\tau + \int_0^1 \left(\frac{\Delta v}{\Delta t} \right)^2 dx + \int_0^t \int_0^1 \left(\frac{\Delta v_x}{\Delta t} \right)^2 dx d\tau$$

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$$\leq C(t) \left[\int_0^1 \left(\frac{\Delta v}{\Delta t} \right)^2 dx \right]_{t=0} + 1 + \int_0^t \int_0^1 \left\{ \left(\frac{\Delta \theta}{\Delta t} \right)^2 + \left(\frac{\Delta \left(\frac{1}{u} \right)}{\Delta t} \right)^2 (\theta^2 + v_x^2) \right\} dx d\tau. \quad (3.36)$$

The right-hand side is bounded when $\Delta t \rightarrow 0$:

$$\begin{aligned} & \overline{\lim}_{\Delta t \rightarrow 0} (\text{the right-hand side}) \\ & \leq C(t) \left[\int_0^1 \left\{ -R \left(\frac{\theta_0}{u_0} \right)' + \mu \left(\frac{v_0'}{u_0} \right)' \right\} dx + 1 + \int_0^t \left\{ \int_0^1 \theta_i^2 dx + \max_{x \in [0,1]} v_x^2 \int_0^1 (\theta^2 + v_x^2) dx \right\} d\tau \right] \\ & \leq C(\epsilon, t) + \epsilon \int_0^t (v_i^2(0, \tau) + v_i^2(1, \tau)) d\tau, \end{aligned}$$

for any $\epsilon > 0$. Therefore the left-hand side of (3.36) is also meaningful when $\Delta t \rightarrow 0$, and we obtain the assertion ([5, Chap.II, Lemma 4.11]). \square

From the previous lemma and (1.1), we recognize that a generalized derivative u_{tt} exists in $L^2((0,1) \times (0,t))$ for any $t > 0$.

Lemma 3.13. *We have*

$$\int_0^1 (v_x^2 + \theta_x^2) dx + \int_0^t \int_0^1 (v_{xx}^2 + \theta_{xx}^2 + \theta_t^2) dx d\tau \leq C(t). \quad (3.37)$$

Proof. The assertion follows from Lemmas 3.9 - 3.12. \square

Hölder estimate (3.1) can be obtained from these lemmas with Sobolev's imbedding theorem, Nirenberg's interpolation theorem and Schauder estimates of the parabolic equations (see [1]).

The existence of a generalized derivative $\theta_{xt} \in L^2((0,1) \times (0,t))$ can be obtained in the similar manner to Lemma 3.12 by use of (1.3).

4. Asymptotic behavior.

In this section, we shall investigate the asymptotic behavior of the solution under the additional assumptions (2.1) and (2.2). It is easy from these to see that there exist positive numbers \bar{P} and M_P such that

$$\lim_{t \rightarrow +\infty} P(t) = \bar{P}, \quad (4.1)$$

$$\sup_{t \in (0, +\infty)} P(t) = M_P. \quad (4.2)$$

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Under these assumptions, looking back the proofs of Lemmas 3.1 - 3.4, we obtain

Lemma 4.1. *We have*

$$\int_0^1 (v^2 + \theta + u) dx + U(t) + \int_0^t V(\tau) d\tau \leq C, \quad (4.3)$$

$$C^{-1} \leq B(x, t) \leq C, \quad (4.4)$$

$$M_\theta(t) \leq C(1 + M_u(t)V(t)). \quad (4.5)$$

The constant C does not depend on t .

In consequence of this and next lemmas, constants $C(t)$ in (3.17) and (3.19) do not depend on t . Therefore when we quote these in this and next sections, we should interpret them with the replacement of $C(t)$ with C . We can get some more estimates not depending on t with some revision of the proofs.

Lemma 4.2. *We have*

$$M_u(t) \leq C, \quad (4.6)$$

$$m_u(t) \geq k. \quad (4.7)$$

Here k is a positive constant not depending on t (see Remark after this lemma).

Proof. From (3.8) and (4.5), we have

$$Y(t)M_u(t) \leq C \left(1 + \int_0^t Y(\tau) d\tau + \int_0^t M_u(\tau) V(\tau) Y(\tau) d\tau \right).$$

Applying Gronwall's lemma, we get

$$M_u(t) \leq CY^{-1}(t) \left(1 + \int_0^t Y(\tau) d\tau \right) \exp \left(C \int_0^t V(\tau) d\tau \right) \leq CY^{-1}(t) \left(1 + \int_0^t Y(\tau) d\tau \right). \quad (4.8)$$

Here we use (4.3). From the definition (3.10) of $Y(t)$ and the assumption (2.1) on $P(t)$,

$$\lim_{t \rightarrow +\infty} Y^{-1}(t) = 0, \quad (4.9)$$

and

$$\begin{aligned} \int_0^t Y^{-1}(t) Y(\tau) d\tau &= \int_0^t \exp \left\{ -\frac{1}{\mu} \int_\tau^t P(s) ds \right\} d\tau \\ &\leq \int_0^t \exp \left\{ -\frac{m_P}{\mu} (t - \tau) \right\} d\tau \leq \frac{\mu}{m_P}. \end{aligned} \quad (4.10)$$

From (4.8) - (4.10), we get (4.6).

To get (4.7), dividing both sides of (1.3) by θ and integrating over $[0, 1] \times [0, t]$,

$$\begin{aligned} \int_0^1 (c_V \log \theta_0 + R \log u_0) dx &\leq \int_0^1 (c_V \log \theta + R \log u) dx \\ &\leq c_V \log \left\{ \int_0^1 \theta dx \right\} + R \log \left\{ \int_0^1 u dx \right\}. \end{aligned}$$

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Here we use Jensen's inequality. Thus,

$$\theta(y(t), t) = \int_0^1 \theta \, dx \geq C \left(\int_0^1 u \, dx \right)^{-\frac{R}{C_V}} \geq C > 0. \quad (4.11)$$

Here $y(t)$ is the same as in Lemma 3.4. Therefore, we have

$$\begin{aligned} \theta^{\frac{1}{2}}(x, t) &= \theta^{\frac{1}{2}}(y(t), t) + \int_{y(t)}^x \frac{\theta_x(\xi, t)}{2\theta^{\frac{1}{2}}(\xi, t)} d\xi \\ &\geq \left\{ \int_0^1 \theta \, dx \right\}^{\frac{1}{2}} \left\{ 1 - \frac{1}{2} \left(M_u(t) \int_0^1 \frac{\theta_x^2}{u\theta^2} dx \right)^{\frac{1}{2}} \right\} \\ &\geq C - \bar{C} V^{\frac{1}{2}}(t), \end{aligned}$$

i.e.,

$$\theta \geq C(1 - V(t)).$$

From (3.8), we have

$$m_u(t) \geq CY^{-1}(t) \left(1 + \int_0^t Y(\tau) d\tau - \int_0^t Y(\tau) V(\tau) d\tau \right). \quad (4.12)$$

Since $V(t) (\geq 0) \in L^1(0, +\infty)$, for any $\epsilon > 0$ there exists $T_1 = T_1(\epsilon)$ such that

$$\int_{T_1}^{+\infty} V(\tau) d\tau < \epsilon. \quad (4.13)$$

When $t \geq T_1$,

$$\begin{aligned} Y^{-1}(t) \int_0^t Y(\tau) d\tau &\geq \int_0^t \exp \left\{ -\frac{1}{\mu} \int_{\tau}^t P(s) ds \right\} d\tau \\ &\geq \int_0^t \exp \left\{ -\frac{M_P}{\mu} (t - \tau) \right\} d\tau \\ &\geq \frac{\mu}{M_P} \left\{ 1 - \exp \left\{ -\frac{M_P}{\mu} T_1 \right\} \right\}. \end{aligned} \quad (4.14)$$

From (2.1), $Y(t)$ is a monotone increasing function of t , so we have

$$\begin{aligned} 0 &\leq Y^{-1}(t) \int_0^t Y(\tau) V(\tau) d\tau \\ &= Y^{-1}(t) \int_0^{T_1} Y(\tau) V(\tau) d\tau + Y^{-1}(t) \int_{T_1}^t Y(\tau) V(\tau) d\tau \\ &\leq Y^{-1}(t) Y(T_1) \int_0^{+\infty} V(\tau) d\tau + \int_{T_1}^t V(\tau) d\tau \\ &\leq C \exp \left\{ -\frac{1}{\mu} \int_{T_1}^t P(\tau) d\tau \right\} + \epsilon \\ &\leq C \exp \left\{ -\frac{m_P}{\mu} (t - T_1) \right\} + \epsilon, \end{aligned} \quad (4.15)$$

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from (4.3) and (4.13). From (4.12), (4.14) and (4.15), if ϵ is sufficiently small and $T_2 (\geq T_1(\epsilon))$ is sufficiently large, then for $t \geq T_2$,

$$m_u(t) \geq \frac{\mu}{2M_p}.$$

Therefore, taking into account of (3.14), we have

$$m_u(t) \geq \min \left\{ \frac{\mu}{2M_p}, C^{-1}(T_2) \right\},$$

where $C^{-1}(t)$ is the same as in (3.14). \square

Remark. It seems that the constant k in the previous lemma can not be expressed explicitly by the constants R, μ, c_v, κ and the initial data.

Lemma 4.3. *We have*

$$\int_0^1 (v^4 + \theta^2) dx + \int_0^t \left\{ \int_0^1 (\theta_x^2 + v^2 v_x^2) dx + \int_0^1 v^2 dx \cdot \int_0^1 v_x^2 dx \right\} d\tau \leq C(k). \quad (4.16)$$

Proof. The proof is almost the same as of Lemma 3.6. w is the same as in Lemma 3.6. From (1.2), (1.3) and (1.6), we have

$$\begin{aligned} (w - c_v \int_0^1 \theta dx)_t &= vv_t + c_v \theta_t - (c_v \int_0^1 \theta dx)_t \\ &= \left(-R \frac{\theta v}{u} + \mu \frac{vv_x}{u} + \kappa \frac{\theta_x}{u} \right)_x - \int_0^1 \left(-R \frac{\theta v_x}{u} + \mu \frac{v_x^2}{u} \right) dx. \end{aligned}$$

Therefore, by use of (2.1) and (4.2) we have

$$\begin{aligned} & \left\{ \frac{1}{2} \int_0^1 (w - c_v \int_0^1 \theta d\xi)^2 dx \right\}_t \\ &= \int_0^1 \left(-R \frac{\theta v}{u} + \mu \frac{vv_x}{u} + \kappa \frac{\theta_x}{u} \right)_x (w - c_v \int_0^1 \theta d\xi) dx \\ & \quad - \int_0^1 (w - c_v \int_0^1 \theta d\xi) dx \cdot \int_0^1 \left(-R \frac{\theta v_x}{u} + \mu \frac{v_x^2}{u} \right) dx \\ &= P(t) \left[-\frac{1}{2} v^3(1, t) + \frac{1}{2} v^3(0, t) \right. \\ & \quad \left. + c_v v(1, t) \left\{ \int_0^1 \theta dx - \theta(1, t) \right\} - c_v v(0, t) \left\{ \int_0^1 \theta dx - \theta(0, t) \right\} \right] \\ & \quad - \int_0^1 \left(-R \frac{\theta v}{u} + \mu \frac{vv_x}{u} + \kappa \frac{\theta_x}{u} \right) (vv_x + c_v \theta_x) dx \\ & \quad - \int_0^1 \frac{1}{2} v^2 dx \cdot \int_0^1 \left(-R \frac{\theta v_x}{u} + \mu \frac{v_x^2}{u} \right) dx \end{aligned}$$

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$$\begin{aligned}
&\leq C \left[|v(1,t)|^3 + |v(0,t)|^3 \right. \\
&\quad + \left| v(1,t) \left\{ \int_0^1 \theta \, dx - \theta(1,t) \right\} \right| + \left| v(0,t) \left\{ \int_0^1 \theta \, dx - \theta(0,t) \right\} \right| \\
&\quad - \frac{\kappa c_V}{2} \int_0^1 \frac{\theta_x^2}{u} \, dx + C \int_0^1 \left(\frac{\theta^2 v^2}{u} + \frac{v^2 v_x^2}{u} \right) \, dx \\
&\quad - \left(\frac{\mu}{2} - \epsilon \right) \int_0^1 v^2 \, dx \cdot \int_0^1 \frac{v_x^2}{u} \, dx + C(\epsilon) \int_0^1 v^2 \, dx \cdot \int_0^1 \theta^2 \, dx.
\end{aligned}$$

for any $\epsilon > 0$. Taking ϵ sufficiently small, and taking into account of (4.6) and (4.7), we obtain

$$\begin{aligned}
&\left\{ \int_0^1 \left(w - c_V \int_0^1 \theta \, d\xi \right)^2 \, dx \right\}_t + \int_0^1 \theta_x^2 \, dx + \int_0^1 v^2 \, dx \cdot \int_0^1 v_x^2 \, dx \\
&\leq C \left[|v(1,t)|^3 + |v(0,t)|^3 + \left| v(1,t) \left\{ \int_0^1 \theta - \theta(1,t) \right\} \right| \right. \\
&\quad \left. + \left| v(0,t) \left\{ \int_0^1 \theta - \theta(0,t) \right\} \right| + \int_0^1 \frac{v^2 v_x^2}{u} \, dx + k \max_{x \in [0,1]} v^2 \int_0^1 \theta^2 \, dx \right]. \quad (4.17)
\end{aligned}$$

From (3.16) and (3.17), we have

$$|v|^3 \leq \epsilon \int_0^1 v^2 v_x^2 \, dx + C(\epsilon) V(t), \quad (4.18)$$

and

$$\left| v \left(\int_0^1 \theta \, dx - \theta \right) \right| \leq C V^{\frac{1}{2}}(t) \left| \int_{y(t)}^x \theta_x \, dx \right| \leq \epsilon \int_0^1 \theta_x^2 \, dx + C(\epsilon) V(t), \quad (4.19)$$

where $y(t)$ is the same as in Lemma 3.4.

From (4.17) - (4.19) with ϵ sufficiently small, (3.17) and (3.19), we get

$$\begin{aligned}
&\left[\int_0^1 \left\{ \left(w - c_V \int_0^1 \theta \, d\xi \right)^2 + C v^4 \right\} \, dx \right]_t + \int_0^1 (\theta_x^2 + v^2 v_x^2) \, dx + \int_0^1 v^2 \, dx \cdot \int_0^1 v_x^2 \, dx \\
&\leq C V(t) \left(1 + k \int_0^1 \theta^2 \, dx \right). \quad (4.20)
\end{aligned}$$

On the other hand, we have

$$\int_0^1 \left(w - c_V \int_0^1 \theta \, d\xi \right)^2 \, dx = \int_0^1 w^2 \, dx - 2c_V \int_0^1 w \, dx \cdot \int_0^1 \theta \, dx + c_V^2 \left(\int_0^1 \theta \, dx \right)^2. \quad (4.21)$$

From (4.3), we have

$$\int_0^1 w \, dx \cdot \int_0^1 \theta \, dx \leq \left\{ \int_0^1 w^2 \, dx \right\}^{\frac{1}{2}} \int_0^1 \theta \, dx \leq \frac{1}{2} \int_0^1 w^2 \, dx + C. \quad (4.22)$$

Integrating (4.20) over $[0, t]$, and by use of (4.3), (4.21) and (4.22), we have

$$\int_0^1 w^2 \, dx + \int_0^t \left\{ \int_0^1 (\theta_x^2 + v^2 v_x^2) \, dx + \int_0^1 v^2 \, dx \cdot \int_0^1 v_x^2 \, dx \right\} \, d\tau$$

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$$\leq C + C(k) \int_0^t V(\tau) \int_0^1 w^2 dx d\tau.$$

Applying Gronwall's lemma, we get the assertion. \square

Lemma 4.4. *We have*

$$\int_0^1 u_x^2 dx + \int_0^t \int_0^1 \theta u_x^2 dx d\tau \leq C(k). \quad (4.23)$$

Proof. Multiplying (1.2) by $(\log u)_x$, and integrating over $[0,1]$, we have

$$\begin{aligned} & \frac{\mu}{2} \left[\int_0^1 \left\{ (\log u)_x \right\}^2 dx \right]_t + \int_0^1 R \frac{\theta}{u} \left(\frac{u_x}{u} \right)^2 dx \\ &= \left\{ \int_0^1 v (\log u)_x dx \right\}_t - \int_0^1 \left\{ v \left(\frac{v_x}{u} \right)_x - R \frac{\theta_x u_x}{u^2} \right\} dx \\ &= \left\{ \int_0^1 v (\log u)_x dx \right\}_t + \int_0^1 \left\{ \frac{v_x^2}{u} + R \frac{\theta_x u_x}{u^2} \right\} dx - \left[v \left(\frac{v_x}{u} \right) \right]_{x=0}^{x=1}. \end{aligned} \quad (4.24)$$

Multiplying (1.2) by v , and integrating over $[0,1]$, we have

$$\frac{1}{2} \left(\int_0^1 v^2 dx \right)_t = \left[\mu v \left(\frac{v_x}{u} \right) \right]_{x=0}^{x=1} - \int_0^1 \left\{ \mu \frac{v_x^2}{u} - R \frac{\theta v u_x}{u^2} + R \frac{\theta_x v}{u} \right\} dx. \quad (4.25)$$

From (4.24) and (4.25), we have

$$\begin{aligned} & \frac{1}{2} \left[\int_0^1 \left\{ \left(\mu (\log u)_x \right)^2 + v^2 \right\} dx \right]_t + \int_0^1 R \mu \frac{\theta}{u} \left(\frac{u_x}{u} \right)^2 dx \\ &= \mu \left\{ \int_0^1 v (\log u)_x dx \right\}_t + \int_0^1 R \left\{ \mu \frac{\theta_x u_x}{u^2} + \frac{\theta v u_x}{u^2} - \frac{\theta_x v}{u} \right\} dx. \end{aligned}$$

Integrating over $[0,t]$ by use of Lemma 4.2, we have

$$\begin{aligned} & \int_0^1 (u_x^2 + v^2) dx + \int_0^t \int_0^1 \theta u_x^2 dx d\tau \\ &\leq C(k) \left\{ 1 + \int_0^1 |v u_x| dx + \int_0^t \int_0^1 (|\theta_x u_x| + |\theta v u_x| + |\theta_x v|) dx d\tau \right\} \\ &\leq \frac{1}{2} \left(\int_0^1 u_x^2 dx + \int_0^t \int_0^1 \theta u_x^2 dx d\tau \right) \\ &\quad + C(k) \left\{ 1 + \int_0^1 v^2 dx + \int_0^t \int_0^1 \left(\frac{\theta_x^2}{\theta} + \theta v^2 + \theta_x^2 + v^2 \right) dx d\tau \right\}. \end{aligned}$$

From (4.16), (4.3) and (3.17), we have

$$\begin{aligned} & \int_0^t \int_0^1 \left(\frac{\theta_x^2}{\theta} + \theta v^2 + \theta_x^2 + v^2 \right) dx d\tau \\ &\leq C(k) \int_0^t \left\{ \int_0^1 \left(\frac{M_u \theta_x^2}{u \theta^2} + \theta_x^2 \right) dx + \max_{x \in [0,1]} v^2 \left(1 + \int_0^1 \theta dx \right) \right\} d\tau \\ &\leq C(k) \int_0^t \left\{ V(\tau) + \int_0^1 \theta_x^2 dx \right\} d\tau \leq C(k). \end{aligned}$$

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Thus, we get the assertion. \square

Lemma 4.5. *If there exist a positive function $\epsilon_1(x, t)$ and positive constants $\epsilon_2, \epsilon_3, \epsilon_4$ such that*

$$\frac{\mu}{u} - \epsilon_1 - \frac{1}{4\epsilon_1 u^2} \left(\epsilon_2 + \frac{\mu^2 R}{c_V + R} \right) \geq \epsilon_3 > 0, \quad (4.26)$$

$$\epsilon_1(x, t) \geq \epsilon_4 > 0 \quad (4.27)$$

for $t \geq 0$, then there exists a constant $C(\epsilon_2, \epsilon_3, \epsilon_4, k)$ which tends to infinity as $\epsilon_i \rightarrow +0$ ($i = 2, 3, 4$), such that

$$\int_0^t \int_0^1 v_x^2 dx d\tau \leq C(\epsilon_2, \epsilon_3, \epsilon_4, k) \quad (4.28)$$

holds.

Proof. From (1.5) and (4.3), we can rewrite (4.25) as follows:

$$\begin{aligned} \frac{1}{2} \int_0^1 v^2(x, t) dx &= \frac{1}{2} \int_0^1 v_0^2(x) dx + \int_0^t \int_0^1 \left\{ \left(R \frac{\theta}{u} - P \right) v_x - \mu \frac{v_x^2}{u} \right\} dx d\tau \\ &\leq C + \int_0^t \int_0^1 \left\{ \left(\epsilon_1 - \frac{\mu}{u} \right) v_x^2 + \frac{1}{4\epsilon_1} \left(R \frac{\theta}{u} - P \right)^2 \right\} dx d\tau. \end{aligned} \quad (4.29)$$

Integrating (1.2) over $[0, x]$, by use of (1.5) we have

$$\left(\int_0^x v d\xi \right)_t = \left(-R \frac{\theta}{u} + P \right) + \mu \frac{v_x}{u}. \quad (4.30)$$

Multiplying both sides by $R \frac{\theta}{u} - P$, and integrating over $[0, 1] \times [0, t]$, we get the estimate as follows:

$$\begin{aligned} &\int_0^t \int_0^1 \left(R \frac{\theta}{u} - P \right)^2 dx d\tau \\ &= \int_0^t \int_0^1 \left\{ \left(P - R \frac{\theta}{u} \right) \left(\int_0^x v d\xi \right)_t + \mu \frac{v_x}{u} \left(R \frac{\theta}{u} - P \right) \right\} dx d\tau \\ &= \left[\int_0^1 \left(P - R \frac{\theta}{u} \right) \int_0^x v d\xi dx \right]_{\tau=0}^{\tau=t} - \int_0^t \int_0^1 \left\{ P' - R \left(\frac{\theta}{u} \right)_t \right\} \int_0^x v d\xi dx d\tau \\ &\quad + \int_0^t \int_0^1 \mu \left\{ R \frac{v_x \theta}{u^2} - P (\log u)_t \right\} dx d\tau \\ &\leq C + \left[\left(\int_0^1 v^2 dx \right)^{\frac{1}{2}} \left(M_P + \frac{R}{m_u} \int_0^1 \theta dx \right) \right]_{\tau=0}^{\tau=t} + \left(\int_0^1 v^2 dx \right)^{\frac{1}{2}} \text{TV}(P) \\ &\quad + R \int_0^t \int_0^1 \left\{ - \left(\frac{R}{c_V} + 1 \right) \frac{\theta v_x}{u^2} + \frac{\mu}{c_V} \frac{v_x^2}{u^2} + \frac{\kappa}{c_V} \left(\frac{\theta_x}{u} \right)_x \frac{1}{u} \right\} \int_0^x v d\xi dx d\tau \\ &\quad + \int_0^t \int_0^1 \mu R \frac{v_x \theta}{u^2} dx d\tau - \left[\mu \int_0^1 P \log u dx \right]_{\tau=0}^{\tau=t} + \mu \int_0^t \int_0^1 P' \log u dx \end{aligned}$$

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$$\begin{aligned}
&\leq C(k) + R \left(\frac{R}{c_V} + 1 \right) \int_0^t \int_0^1 \left\{ \frac{\theta v^2}{u^2} + \left(\frac{\theta_x v}{u^2} - \frac{\theta u_x v}{u^3} \right) \int_0^x v \, d\xi \right\} dx d\tau \\
&\quad + \frac{\mu R}{c_V} \int_0^t \left(\int_0^1 v^2 dx \right)^{\frac{1}{2}} \int_0^1 \frac{v_x^2}{u^2} dx d\tau - \frac{\kappa R}{c_V} \int_0^t \int_0^1 \left(\frac{\theta_x v}{u^2} - \frac{\theta_x u_x}{u^3} \int_0^x v \, d\xi \right) dx d\tau \\
&\quad + \int_0^t \int_0^1 \mu R \frac{v_x \theta}{u^2} dx d\tau \\
&\leq C(k) \left[1 + \int_0^t \left\{ \max_{x \in [0,1]} v^2 \int_0^1 \theta \, dx \right. \right. \\
&\quad \left. \left. + \left(\int_0^1 v^2 dx \right)^{\frac{1}{2}} \left(\int_0^1 (\theta_x^2 + v^2 + \theta u_x^2) dx + \max_{x \in [0,1]} v^2 \int_0^1 \theta \, dx \right) \right\} d\tau \right. \\
&\quad \left. + \int_0^t \int_0^1 \left\{ \theta_x^2 + v^2 + \left(\theta u_x^2 + \frac{\theta_x^2}{\theta^2} + \theta_x^2 \right) \left(\int_0^1 v^2 dx \right)^{\frac{1}{2}} \right\} dx d\tau \right] \\
&\quad + \int_0^t \left\{ \epsilon_2 \int_0^1 \frac{v_x^2}{u^2} dx + \frac{c_V^2 C(k)}{4 \epsilon_2 \mu^2 R^2} \int_0^1 v^2 dx \int_0^1 v_x^2 dx \right\} d\tau \\
&\quad + \int_0^t \int_0^1 \mu R \frac{v_x \theta}{u^2} dx d\tau \\
&\leq C(\epsilon_2, k) + \epsilon_2 \int_0^t \int_0^1 \frac{v_x^2}{u^2} dx d\tau + \int_0^t \int_0^1 \mu R \frac{v_x \theta}{u^2} dx d\tau. \tag{4.31}
\end{aligned}$$

Here we use (1.1), (4.3), (4.7), (1.9), (1.5), (3.17) and Lemmas 4.3 - 4.4. The last term can be calculated by use of (1.1) and (1.3) as follows:

$$\begin{aligned}
\int_0^t \int_0^1 \frac{v_x \theta}{u^2} dx d\tau &= - \int_0^t \int_0^1 \left(\frac{1}{u} \right)_t \theta dx d\tau \\
&= \left[- \int_0^1 \frac{\theta}{u} dx \right]_{\tau=0}^{\tau=t} + \int_0^t \int_0^1 \frac{\theta_t}{u} dx d\tau \\
&= \left[- \int_0^1 \frac{\theta}{u} dx \right]_{\tau=0}^{\tau=t} + \frac{1}{c_V} \int_0^t \int_0^1 \left\{ - R \frac{\theta v_x}{u^2} + \mu \frac{v_x^2}{u^2} + \kappa \left(\frac{\theta_x}{u} \right)_x \frac{1}{u} \right\} dx d\tau.
\end{aligned}$$

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Therefore from (1.5), (4.3) and Lemmas 4.3 - 4.4, we have

$$\begin{aligned} \int_0^t \int_0^1 \frac{\theta v_x}{u^2} dx d\tau &= \frac{1}{c_V + R} \left\{ c_V \left[- \int_0^1 \frac{\theta}{u} dx \right]_{\tau=0}^{\tau=t} + \int_0^t \int_0^1 \left(\mu \frac{v_x^2}{u^2} + \kappa \frac{\theta_x u_x}{u^3} \right) dx d\tau \right\} \\ &\leq C(k) \left\{ 1 + \int_0^t \int_0^1 \left(\theta_x^2 + \frac{\theta^2}{\theta^2} + \theta u_x^2 \right) dx d\tau \right\} + \frac{\mu}{c_V + R} \int_0^t \int_0^1 \frac{v_x^2}{u^2} dx d\tau \\ &\leq C(k) + \frac{\mu}{c_V + R} \int_0^t \int_0^1 \frac{v_x^2}{u^2} dx d\tau \end{aligned} \quad (4.32)$$

Combining (4.27) and (4.29) - (4.32), we have

$$\frac{1}{2} \int_0^1 v^2 dx + \int_0^t \int_0^1 \left\{ \frac{\mu}{u} - \epsilon_1 - \frac{1}{4\epsilon_1 u^2} \left(\epsilon_2 + \frac{\mu^2 R}{c_V + R} \right) \right\} v_x^2 dx d\tau \leq C(\epsilon_2, \epsilon_4, k).$$

This gives the assertion. \square

Lemma 4.6. *There always exist $\epsilon_1(x, t)$, ϵ_2 , ϵ_3 , and ϵ_4 .*

Proof. Consider a function $\Phi(\zeta; u)$ of ζ with a parameter u :

$$\Phi(\zeta; u) = -\zeta^2 + \frac{\mu}{u} \zeta - \frac{1}{4u^2} \left(\epsilon_2 + \frac{\mu^2 R}{c_V + R} \right).$$

Maximum value of Φ is

$$\max_{\zeta} \Phi(\zeta; u) = \Phi\left(\frac{\mu}{2u}; u\right) = \frac{\mu^2 c_V - \epsilon_2(c_V + R)}{4u^2(c_V + R)}. \quad (4.33)$$

We choose ϵ_2 sufficiently small such that

$$\max_{\zeta} \Phi(\zeta; u) > 0.$$

The condition (4.26) can be rewrite as follows:

$$\Phi(\epsilon_1(x, t); u(x, t)) \geq \epsilon_3 \epsilon_1(x, t) > 0. \quad (4.34)$$

So we choose

$$\epsilon_1(x, t) = \frac{\mu}{2u(x, t)}. \quad (4.35)$$

From (4.6), the constant ϵ_4 exists, and (4.27) holds. From (4.33), (4.35) and (4.6), we can choose ϵ_3 such that

$$\frac{\Phi(\epsilon_1(x, t); u(x, t))}{\epsilon_1(x, t)} = \frac{\mu^2 c_V - \epsilon_2(c_V + R)}{2\mu(c_V + R)u(x, t)} \geq \frac{\mu^2 c_V - \epsilon_2(c_V + R)}{2\mu(c_V + R)C} \geq \epsilon_3,$$

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so (4.34) holds. \square

Lemma 4.7. *We have*

$$\int_0^t \int_0^1 \left(R \frac{\theta}{u} - P \right)^2 dx d\tau \leq C(k), \quad (4.36)$$

$$\lim_{t \rightarrow +\infty} \int_0^1 v^2(x, t) dx = 0. \quad (4.37)$$

Proof. (4.36) follows from (4.31), (4.32) and (4.28).

To prove (4.37), we rewrite (4.25) again as follows:

$$\int_0^t \left| \frac{d}{dt} \int_0^1 v^2 dx \right| d\tau \leq \int_0^t \int_0^1 \left\{ \left(R \frac{\theta}{u} - P \right)^2 + C(k) v_x^2 \right\} dx d\tau.$$

Since the right-hand side is bounded from (4.28) and (4.36), $\lim_{t \rightarrow +\infty} \int_0^1 v^2 dx$ exists. On the other hand,

$\int_0^1 v^2 dx \in L^1(0, +\infty)$ (see (3.17) and (4.3)). Therefore the limit must be zero. \square

Lemma 4.8. *u and $\int_0^1 \theta dx$ have limits as $t \rightarrow +\infty$:*

$$u(x, t) \rightarrow \bar{u} \quad \text{as } t \rightarrow +\infty \quad (4.38)$$

uniformly in $x \in [0, 1]$, and

$$\int_0^1 \theta dx \rightarrow \bar{\theta} \quad \text{as } t \rightarrow +\infty, \quad (4.39)$$

where \bar{u} and $\bar{\theta}$ are positive constants given by (2.3) and (2.4).

Proof. In order to prove the convergence of u , it is enough to show that for any $\epsilon > 0$, there exists $T_3 > 0$ such that

$$|u(x, t) - u(0, t)| < C \cdot \epsilon, \quad (4.40)$$

and

$$\left| \int_0^1 u(x, t) dx - \bar{u} \right| < C \cdot \epsilon \quad (4.41)$$

uniformly in $x \in [0, 1]$ for $t \geq T_3$. Indeed (4.40) implies

$$\left| u(x, t) - \int_0^1 u(x, t) dx \right| < C \cdot \epsilon$$

uniformly in $x \in [0, 1]$ for $t \geq T_3$.

In the similar way to Lemma 3.3, we have

$$u(x, t) = \frac{1}{B(x, t; T_4)Y(t; T_4)} \left(u(x, T_4) + \int_{T_4}^t \frac{R}{\mu} \theta(x, \tau) B(x, \tau; T_4) Y(\tau; T_4) d\tau \right), \quad (4.42)$$

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where

$$B(x, t; T_4) = \exp \left\{ \frac{1}{\mu} \int_0^x (v(\xi, T_4) - v(\xi, t)) d\xi \right\}, \quad (4.43)$$

$$Y(t; T_4) = \exp \left\{ \frac{1}{\mu} \int_{T_4}^t P(\tau) d\tau \right\} \quad (4.44)$$

for any $T_4 \in (0, T_3)$.

From (4.43), we have

$$\begin{aligned} & \exp \left\{ - \frac{1}{\mu} \left(\left(\int_0^1 v^2(\xi, t) d\xi \right)^{\frac{1}{2}} + \left(\int_0^1 v^2(\xi, \tau) d\xi \right)^{\frac{1}{2}} \right) \right\} \\ & \leq \frac{B(x, \tau; T_4)}{B(x, t; T_4)} \leq \exp \left\{ \frac{1}{\mu} \left(\left(\int_0^1 v^2(\xi, t) d\xi \right)^{\frac{1}{2}} + \left(\int_0^1 v^2(\xi, \tau) d\xi \right)^{\frac{1}{2}} \right) \right\}. \end{aligned} \quad (4.45)$$

Therefore because of (4.3), (4.6), (4.16), (4.28), (4.37), (4.44) and (4.45) we can choose

$T_4 = T_4(\epsilon)$ such that

$$\begin{cases} \max_{x \in [0, 1]} \left| \frac{B(x, \tau; T_4)}{B(x, t; T_4)} - 1 \right| < \epsilon, \\ \int_{T_4}^t \int_0^1 (\theta_x^2 + v_x^2) dx d\tau < \epsilon^2, \\ \left| \int_0^1 u(x, t) \int_0^x v(\xi, t) d\xi dx \right| < \epsilon, \\ \left| \frac{1}{\mu} \left(\frac{P(t)}{\mu} \int_0^1 u(x, t) \int_0^x v(\xi, t) d\xi dx - \int_0^1 v^2(x, t) dx \right) \right| < \epsilon \end{cases} \quad (4.46)$$

for $t \geq \tau \geq T_4$. Next we choose $T_3 (> T_4)$ such that

$$\begin{cases} \frac{u(x, T_4)}{B(x, t; T_4)Y(t; T_4)} + \frac{u(0, T_4)}{Y(t; T_4)} < \epsilon, \\ \left| \frac{1}{Y(t; T_4)} \int_0^1 u(x, T_4) dx \right| < \epsilon, \\ \left| \frac{1}{\mu Y(t; T_4)} \int_0^1 u(x, T_4) \int_0^x v(\xi, T_4) d\xi dx \right| < \epsilon \end{cases} \quad (4.47)$$

for $t \geq T_3$. It is possible to choose T_3 as above by use of (4.6), (4.3), (4.43), (4.44) and (2.1).

From (4.42), we have

$$\begin{aligned} |u(x, t) - u(0, t)| & \leq \frac{u(x, T_4)}{B(x, t; T_4)Y(t; T_4)} + \frac{u(0, T_4)}{Y(t; T_4)} \\ & + \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{R}{\mu} \left(\int_0^1 \theta dx + 1 + \frac{1}{4} \int_0^1 \theta_x^2 dx \right) \left| \frac{B(x, \tau; T_4)}{B(x, t; T_4)} - 1 \right| Y(\tau; T_4) d\tau \end{aligned}$$

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$$\begin{aligned}
 & + \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{R}{\mu} \left(\epsilon + \frac{1}{4\epsilon} \int_0^1 \theta_x^2(x, \tau) dx \right) Y(t; T_4) d\tau \\
 & \leq C \cdot \epsilon + C \cdot \epsilon \int_{T_4}^t \frac{Y(\tau; T_4)}{Y(t; T_4)} d\tau \\
 & \leq C \cdot \epsilon.
 \end{aligned}$$

Here we use (4.46), (4.47), (4.3) and (2.1), and estimate the integral $\int_{T_4}^t \frac{Y(\tau; T_4)}{Y(t; T_4)} d\tau$ in the similar way to (4.10). Thus we have shown (4.40).

Before proving (4.41), we must have some calculations. From (2.2) and (4.6)

$$\lim_{t \rightarrow +\infty} \int_0^t P'(\tau) \int_0^1 u(x, \tau) dx d\tau$$

exists. By L'Hospital's theorem, we have

$$\begin{aligned}
 & \lim_{t \rightarrow +\infty} \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) \int_0^1 (c_V \theta + Pu)(x, \tau) dx d\tau \\
 & = \lim_{t \rightarrow +\infty} \frac{\frac{1}{\mu} Y(t; T_4) \int_0^1 (c_V \theta + Pu)(x, t) dx}{\frac{1}{\mu} P(t) Y(t; T_4)} \\
 & = \lim_{t \rightarrow +\infty} \frac{1}{P(t)} \left\{ \int_0^1 \left(\frac{1}{2} v_0^2 + c_V \theta_0 + P(0) u_0 \right) dx \right. \\
 & \quad \left. + \int_0^t P'(\tau) \int_0^1 u(x, \tau) dx d\tau - \int_0^1 \frac{1}{2} v^2(x, t) dx \right\} \\
 & = \frac{c_V + R}{R} \cdot \bar{u}.
 \end{aligned}$$

Here we use (3.4) and (4.37). Therefore (if necessary, we reset T_3 larger,) we may assume that

$$\left| \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) \int_0^1 (c_V \theta + Pu) dx d\tau - \frac{c_V + R}{R} \cdot \bar{u} \right| < \epsilon \quad (4.48)$$

for $t \geq T_3$.

Now we multiply both sides of (4.30) by u , and integrate over $[0, 1]$. We get

$$\begin{aligned}
 \int_0^1 R \theta dx & = \int_0^1 Pu dx + \mu \int_0^1 v_x dx - \left(\int_0^1 u \int_0^x v d\xi dx \right)_t + \int_0^1 u_t \int_0^x v d\xi dx \\
 & = \int_0^1 Pu dx + \left(\mu \int_0^1 u dx - \int_0^1 u \int_0^x v d\xi dx \right)_t - \int_0^1 v^2 dx.
 \end{aligned} \quad (4.49)$$

Here we use (1.1) and (1.9). Therefore, we have

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$$\begin{aligned}
& \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) \int_0^1 R \theta(x, \tau) dx d\tau \\
&= \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) \left\{ \int_0^1 P u dx + \left(\mu \int_0^1 u dx - \int_0^1 u \int_0^x v d\xi dx \right)_t - \int_0^1 v^2 dx \right\} d\tau \\
&= \frac{1}{Y(t; T_4)} \left\{ \left[Y(\tau; T_4) \int_0^1 u(x, \tau) dx - \frac{1}{\mu} Y(\tau; T_4) \int_0^1 u(x, \tau) \int_0^x v(\xi, \tau) d\xi dx \right]_{\tau=T_4}^{\tau=t} \right. \\
&\quad \left. + \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) \left(\frac{1}{\mu} P(\tau) \int_0^1 u(x, \tau) \int_0^x v(\xi, \tau) d\xi dx - \int_0^1 v^2(x, \tau) dx \right) d\tau \right\} \\
&= \int_0^1 u(x, t) dx - \frac{1}{\mu} \int_0^1 u(x, t) \int_0^x v(\xi, t) d\xi dx \\
&\quad - \frac{1}{Y(t; T_4)} \int_0^1 u(x, T_4) dx + \frac{1}{\mu Y(t; T_4)} \int_0^1 u(x, T_4) \int_0^x v(\xi, T_4) d\xi dx \\
&\quad + \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) \left(\frac{P(\tau)}{\mu} \int_0^1 u(x, \tau) \int_0^x v(\xi, \tau) d\xi dx - \int_0^1 v^2(x, \tau) dx \right) d\tau. \quad (4.50)
\end{aligned}$$

On the other hand, we have

$$\begin{aligned}
& \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) P(\tau) \int_0^1 u(x, \tau) dx d\tau \\
&= \frac{1}{Y(t; T_4)} \left[Y(\tau; T_4) \int_0^1 u(x, \tau) dx \right]_{\tau=T_4}^{\tau=t} - \frac{1}{Y(t; T_4)} \int_{T_4}^t Y(\tau; T_4) \int_0^1 u(x, \tau) dx d\tau \\
&= \int_0^1 u(x, t) dx - \frac{1}{Y(t; T_4)} \int_0^1 u(x, T_4) dx - \frac{1}{Y(t; T_4)} \int_{T_4}^t Y(\tau; T_4) \int_0^1 v_x(x, \tau) dx d\tau.
\end{aligned}$$

From this and (4.50), we have

$$\begin{aligned}
& \left| \frac{1}{Y(t; T_4)} \int_{T_4}^t \frac{1}{\mu} Y(\tau; T_4) \int_0^1 (c_v \theta + P u)(x, \tau) dx d\tau - \frac{c_v + R}{R} \int_0^1 u(x, t) dx \right| \\
&\leq \frac{c_v}{R} \left| \int_0^1 \frac{1}{\mu} \int_0^1 u(x, t) \int_0^x v(\xi, t) d\xi dx \right| \\
&\quad + \left| \frac{1}{Y(t; T_4)} \left(\int_0^1 u(x, T_4) dx - \frac{1}{\mu} \int_0^1 u(x, T_4) \int_0^x v(\xi, T_4) d\xi dx \right) \right| \\
&\quad + \frac{1}{Y(t; T_4)} \int_{T_4}^t Y(\tau; T_4) \left| \frac{1}{\mu} \left(\frac{P(\tau)}{\mu} \int_0^1 u(x, \tau) \int_0^x v(\xi, \tau) d\xi dx - \int_0^1 v^2(x, \tau) dx \right) \right| d\tau \\
&\quad + \frac{1}{Y(t; T_4)} \int_0^1 u(x, T_4) dx + \epsilon \int_{T_4}^t \frac{Y(\tau; T_4)}{Y(t; T_4)} d\tau + \frac{1}{4\epsilon} \int_{T_4}^t \int_0^1 v_x^2(x, \tau) dx d\tau \\
&\leq C \cdot \epsilon. \quad (4.51)
\end{aligned}$$

The last estimation is a consequence of (4.46) and (4.47).

(4.48) and (4.51) imply (4.41). Taking $t \rightarrow +\infty$ in (3.4), we can easily get (4.39) by use of (4.38). \square

Lemma 4.9. *We have*

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$$\int_0^1 (u_x^2 + v_x^2 + \theta_x^2) dx + \int_0^t \int_0^1 (v_{xx}^2 + \theta_{xx}^2) dx d\tau \leq C(k), \quad (4.52)$$

$$\lim_{t \rightarrow +\infty} \int_0^1 (u_x^2 + v_x^2 + \theta_x^2) dx = 0. \quad (4.53)$$

Proof. The proof is carried out only in the case in which the initial data and $P(t)$ possess the greater regularity such that a classical derivative v_{xt} exists. It is easy by the density argument to see that we can eliminate the need for the extra regularity.

Multiplying (1.2) by $\left\{v_x - \frac{1}{\mu}(R\theta - Pu)\right\}_x$, and integrating over $[0,1]$, by use of (1.1) and (1.5)

we have

$$\begin{aligned} & \left\{ \frac{1}{2} \int_0^1 v_x^2 dx \right\}_t + \int_0^1 \left\{ P \left(\frac{u_x}{u} \right)_t u_x + \mu \frac{v_{xx}^2}{u} + \frac{R^2}{\mu} \frac{\theta_x^2}{u} + \frac{R}{\mu} \frac{P\theta u_x^2}{u^2} \right\} dx \\ &= \int_0^1 \left\{ \frac{1}{\mu} (R\theta - Pu) v_{xt} + R \frac{\theta_x v_{xx}}{u} - R \frac{\theta u_x v_{xx}}{u^2} + \mu \frac{v_x v_{xx} u_x}{u^2} \right. \\ & \quad \left. + \frac{R^2}{\mu} \frac{\theta \theta_x u_x}{u^2} + R \frac{\theta_x v_{xx}}{u} - R \frac{v_x u_x \theta_x}{u^2} + \frac{R}{\mu} \frac{P\theta_x u_x}{u} \right\} dx \\ &\leq \int_0^1 \frac{1}{\mu} (R\theta - Pu) v_{xt} dx + \int_0^1 \frac{\mu}{2} \frac{v_{xx}^2}{u} dx + C(k) \left[\int_0^1 \left(\theta_x^2 + \frac{\theta_x^2}{\theta^2} \right) dx \right. \\ & \quad \left. + \left(\int_0^1 \theta dx + 1 + \int_0^1 \theta_x^2 dx \right) \int_0^1 \theta u_x^2 dx \right. \\ & \quad \left. + \left(C(\epsilon) \int_0^1 v_x^2 dx + \epsilon \int_0^1 v_{xx}^2 dx \right) \int_0^1 u_x^2 dx \right] \end{aligned} \quad (4.54)$$

for any $\epsilon > 0$. Here we use (4.2) and (4.7).

On the other hand, from (1.1), (1.3), (2.2), (4.2), (4.3), (4.6), (4.7), (4.11) and (4.23) we have

$$\begin{aligned} \int_{T_3}^t \int_0^1 P \left(\frac{u_x}{u} \right)_t u_x dx d\tau &= \left[\int_0^1 \frac{Pu}{2} \left(\frac{u_x}{u} \right)^2 (x, \tau) d\tau \right]_{\tau=T_3}^{\tau=t} \\ &\quad - \int_{T_3}^t \int_0^1 \left\{ \frac{P'u}{2} \left(\frac{u_x}{u} \right)^2 + \frac{Pv_x}{2} \left(\frac{u_x}{u} \right)^2 \right\} dx d\tau, \end{aligned} \quad (4.55)$$

$$\int_{T_3}^t \int_0^1 |P'| u_x^2 dx d\tau = \int_{T_3}^t |P'| \int_0^1 u_x^2 dx d\tau \leq C(k) \int_{T_3}^t |P'| d\tau, \quad (4.56)$$

$$\begin{aligned} \int_{T_3}^t \int_0^1 |v_x| u_x^2 dx d\tau &\leq C \int_{T_3}^t \int_0^1 \left\{ v_x^2 + \left(\int_0^1 \theta dx - \theta \right)^2 + \theta^2 \right\} u_x^2 dx d\tau \\ &\leq C \int_{T_3}^t \left\{ \left(C(\epsilon) \int_0^1 v_x^2 dx + \epsilon \int_0^1 v_{xx}^2 dx + \int_0^1 \theta_x^2 dx \right) \int_0^1 u_x^2 dx \right. \\ & \quad \left. + \left(\int_0^1 \theta dx + 1 + \int_0^1 \theta_x^2 dx \right) \int_0^1 \theta u_x^2 dx \right\} d\tau, \end{aligned} \quad (4.57)$$

$$\begin{aligned} \int_{T_3}^t \int_0^1 \frac{1}{\mu} (R\theta - Pu) v_{xt} dx d\tau &= \left[\int_0^1 \frac{1}{\mu} (R\theta - Pu) v_x(x, \tau) dx \right]_{\tau=T_3}^{\tau=t} \\ &\quad - \int_{T_3}^t \int_0^1 \left(-\frac{R^2}{c_V \mu} \frac{\theta v_x}{u} + \frac{R}{c_V} \frac{v_x^2}{u} + \frac{\kappa R}{c_V \mu} \frac{\theta_{xx}}{u} \right. \end{aligned}$$

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$$\begin{aligned}
& - \frac{\kappa R}{c_V \mu} \frac{\theta_x u_x}{u^2} - \frac{1}{\mu} P' u + \frac{1}{\mu} P v_x \Big) v_x dx d\tau \\
& \leq \int_0^1 (\epsilon v_x^2 + C \theta_x^2)(x, t) dx \\
& \quad + C(\epsilon) \int_0^1 \left\{ \int_0^1 R \theta(\xi, t) d\xi - P(t) u(x, t) \right\}^2 dx \\
& \quad + C \int_0^1 \left\{ \left(R \frac{\theta}{u} - P \right)^2 + v_x^2 \right\} (x, T_5) dx \\
& \quad + \int_{T_5}^t \left[C(k) \left\{ \left(\int_0^1 \theta dx + 1 + \int_0^1 \theta_x^2 dx + \int_0^1 v_x^2 dx + |P'| \right) \int_0^1 v_x^2 dx \right. \right. \\
& \quad \left. \left. + \left(C(\epsilon) \int_0^1 v_x^2 dx + \epsilon \int_0^1 v_{xx}^2 dx \right) \int_0^1 u_x^2 dx + |P'| \right\} \right. \\
& \quad \left. + \int_0^1 v_{xx}^2 dx \cdot \int_0^1 v_x^2 dx + C \int_0^1 \theta_{xx}^2 dx \right] d\tau \tag{4.58}
\end{aligned}$$

for any $\epsilon, T_5 > 0$.

We put ϵ sufficiently small and integrate (4.54) over $[T_5, t]$ taking into account of (4.55) - (4.58).

Thus we have

$$\begin{aligned}
& \int_0^1 (u_x^2 + v_x^2)(x, t) dx + \int_{T_5}^t \int_0^1 v_{xx}^2 dx d\tau \\
& \leq C(k) \int_0^1 \left[\left\{ u_x^2 + v_x^2 + \left(R \frac{\theta}{u} - P \right)^2 \right\} (x, T_5) + \left\{ \int_0^1 R \theta(\xi, t) d\xi - P(t) u(x, t) \right\}^2 \right] dx \\
& \quad + C(k) \int_{T_5}^t \left\{ \int_0^1 \left(\theta u_x^2 + v_x^2 + \theta_x^2 + \frac{\theta_x^2}{\theta^2} \right) dx + |P'| \right. \\
& \quad \left. + \int_0^1 (v_x^2 + \theta_x^2) dx \cdot \int_0^1 (\theta u_x^2 + v_x^2 + |P'|) dx \right\} d\tau \\
& \quad + C \int_{T_5}^t \int_0^1 v_{xx}^2 dx \cdot \int_0^1 v_x^2 dx d\tau \\
& \quad + C \left(\int_0^1 \theta_x^2 dx + \int_{T_5}^t \int_0^1 \theta_{xx}^2 dx d\tau \right). \tag{4.59}
\end{aligned}$$

Here we use (2.1), (4.1), (4.3) and (4.23).

Multiplying (1.3) by θ_{xx} , and integrating over $[0, 1] \times [T_5, t]$, we have in the similar manner,

$$\begin{aligned}
& \int_0^1 \theta_x^2(x, t) dx + \int_{T_5}^t \int_0^1 \theta_{xx}^2 dx d\tau \\
& \leq \int_0^1 \theta_x^2(x, T_5) dx + C(k) \int_{T_5}^t \left\{ \int_0^1 (v_x^2 + \theta_x^2) dx + \int_0^1 (v_x^2 + \theta_x^2) dx \cdot \int_0^1 v_x^2 dx \right\} d\tau \\
& \quad + C \int_{T_5}^t \int_0^1 v_{xx}^2 dx \cdot \int_0^1 v_x^2 dx d\tau. \tag{4.60}
\end{aligned}$$

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From (4.59) and (4.60), we have

$$\begin{aligned} & \int_0^1 (u_x^2 + v_x^2 + \theta_x^2)(x, t) dx + \int_{T_5}^t \int_0^1 (v_{xx}^2 + \theta_{xx}^2) dx d\tau \\ & \leq C_1(k) \int_0^1 \left\{ u_x^2 + v_x^2 + \theta_x^2 + \left(R \frac{\theta}{u} - P \right)^2 \right\} (x, T_5) \\ & \quad + \left\{ \int_0^1 R \theta(\xi, t) d\xi - P(t) u(x, t) \right\}^2 dx \\ & \quad + C_2(k) \int_{T_5}^t \left\{ F_1(\tau) + F_2(\tau) \int_0^1 (u_x^2 + v_x^2 + \theta_x^2) dx \right\} d\tau \\ & \quad + C_3 \left\{ \sup_{\tau \in [T_5, t]} \int_0^1 v_x^2(x, \tau) dx \right\} \int_{T_5}^t \int_0^1 v_{xx}^2 dx d\tau \end{aligned}$$

where $F_i(t) \in L^1(0, +\infty)$ ($i = 1, 2$; see (2.2), (4.3), (4.16), (4.23) and (4.28)). Applying Gronwall's lemma,

$$\begin{aligned} & \int_0^1 (u_x^2 + v_x^2 + \theta_x^2)(x, t) dx + \int_{T_5}^t \int_0^1 (v_{xx}^2 + \theta_{xx}^2) dx d\tau \\ & \leq \left\{ C_1(k) \int_0^1 \left\{ u_x^2 + v_x^2 + \theta_x^2 + \left(R \frac{\theta}{u} - P \right)^2 \right\} (x, T_5) \right. \\ & \quad + \left\{ \int_0^1 R \theta(\xi, t) d\xi - P(t) u(x, t) \right\}^2 dx \\ & \quad + C_2(k) \int_{T_5}^t F_1(\tau) d\tau + C_3 \left\{ \sup_{\tau \in [T_5, t]} \int_0^1 v_x^2(x, \tau) dx \right\} \int_{T_5}^t \int_0^1 v_{xx}^2 dx d\tau \Big\} \\ & \quad \times \exp \left\{ C_2(k) \int_{T_5}^t F_2(\tau) d\tau \right\} \end{aligned} \quad (4.61)$$

for $t \geq T_5$.

Since $F_i(t) \in L^1(0, +\infty)$ and Lemma 4.8, for any $\epsilon_5 > 0$, it is possible to put $T_6 > 0$ such that

$$\begin{cases} C_1(k) \int_0^1 \left\{ \int_0^1 R \theta(\xi, t) d\xi - P(t) u(x, t) \right\}^2 dx < \epsilon_5, \\ C_2(k) \int_{T_5}^t F_1(\tau) d\tau < \epsilon_5, \\ \exp \left\{ C_2(k) \int_{T_5}^t F_2(\tau) d\tau \right\} < 1 + \epsilon_5, \end{cases} \quad (4.62)$$

for $t \geq T_5 > T_6$.

Since $\int_0^1 \left\{ \theta u_x^2 + v_x^2 + \theta_x^2 + \left(R \frac{\theta}{u} - P \right)^2 \right\} dx \in L^1(0, +\infty)$ (see (4.16), (4.23), (4.28) and (4.36)),

there exists $T_5 (> T_6)$ such that

$$C_1(k) \int_0^1 \left\{ u_x^2 + v_x^2 + \theta_x^2 + \left(R \frac{\theta}{u} - P \right)^2 \right\} (x, T_5) dx < \epsilon_5. \quad (4.63)$$

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Indeed, if there does not exist T_5 , from (3.12) and (4.7) we have

$$\begin{aligned} +\infty &> \int_{T_6}^{+\infty} \int_0^1 \left\{ \theta u_x^2 + v_x^2 + \theta_x^2 + \left(R \frac{\theta}{u} - P \right)^2 \right\} dx d\tau \\ &\geq \frac{\epsilon_5}{C_1(k)} \int_{T_6}^{+\infty} \min \{1, m_0(\tau)\} d\tau \\ &\geq \frac{\epsilon_5}{C_1(k)} \int_{T_6}^{+\infty} \min \left\{ 1, \frac{C(k)}{1+\tau} \right\} d\tau = +\infty. \end{aligned}$$

This is contradiction.

Thus we have from (4.61) - (4.63),

$$\begin{aligned} &\int_0^1 (u_x^2 + v_x^2 + \theta_x^2)(x, t) dx + \int_{T_5}^t \int_0^1 (v_{xx}^2 + \theta_{xx}^2) dx d\tau \\ &\leq (1 + \epsilon_5) \left\{ 3\epsilon_5 + C_3 \left(\sup_{\tau \in [T_5, t]} \int_0^1 v_x^2(x, \tau) dx \right) \int_{T_5}^t \int_0^1 v_{xx}^2 dx d\tau \right\} \end{aligned} \quad (4.64)$$

for $t \geq T_5$.

We put ϵ_5 such that

$$\max \left\{ \frac{\epsilon_5}{C_1(k)}, 3\epsilon_5(1 + \epsilon_5) \right\} < \frac{1}{2C_3(1 + \epsilon_5)}.$$

Therefore, from (4.63)

$$\int_0^1 v_x^2(x, T_5) dx < \frac{1}{2C_3(1 + \epsilon_5)}.$$

Thus we can define T_7 :

$$T_7 = \sup \left\{ t ; \sup_{\tau \in [T_5, t]} \int_0^1 v_x^2(x, \tau) dx \leq \frac{1}{2C_3(1 + \epsilon_5)} \right\}. \quad (4.65)$$

We assert $T_7 = +\infty$. To prove this we assume $T_7 < +\infty$, so we get from (4.64) with $t = T_7$,

$$\int_0^1 v_x^2(x, T_7) dx \leq 3\epsilon_5(1 + \epsilon_5) < \frac{1}{2C_3(1 + \epsilon_5)}.$$

This conflicts with the definition (4.65) of T_7 , if $T_7 < +\infty$.

Hence from (4.64) and $T_7 = +\infty$, we have

$$\int_0^1 (u_x^2 + v_x^2 + \theta_x^2)(x, t) dx + \int_{T_5}^t \int_0^1 \left(\frac{1}{2} v_{xx}^2 + \theta_{xx}^2 \right) dx d\tau \leq 3\epsilon_5(1 + \epsilon_5)$$

for $t \geq T_5$.

Since $\epsilon_5 > 0$ is arbitrary, it follows from the above estimate that the assertions are valid. \square

From Lemmas 4.7 - 4.9, we can easily show Theorem 2.

5. Concluding remarks.

Remark 5.1. In order to prove the *local* existence theorem, it is enough that $P(t)$ has $C^{\frac{1+\alpha}{2}}$ -smoothness.

We do not know that C^1 -smoothness of $P(t)$ is a necessary condition for proving the *global* existence theorem or not.

Remark 5.2. Under the assumption of Theorem 2, the estimate (4.36) means that the difference between the inner and outer pressure is square integrable on $(0,1) \times (0,+\infty)$.

In this connection, it follows the formula on the integral of the amount $R\theta - Pu$:

$$\int_0^t \int_0^1 (v^2 + R\theta - Pu) dx d\tau = \mu \int_0^1 (u - u_0) dx - \left[\int_0^1 u(x, \tau) \int_0^x v(\xi, \tau) d\xi dx \right]_{\tau=0}^{\tau=t}.$$

from integrating (4.49) over $[0, t]$.

Therefore under the assumption of Theorem 2, by use of (3.17), (4.3), (4.6), (4.37) and (4.38), we conclude that $R\theta - Pu$ is summable on $(0,1) \times (0,+\infty)$ in Riemann's sense, and

$$\int_0^{+\infty} \int_0^1 (R\theta - Pu) dx dt = - \int_0^{+\infty} \int_0^1 v^2 dx dt + \mu \left(\bar{u} - \int_0^1 u_0 dx \right) + \int_0^1 u_0(x) \int_0^x v_0(\xi) d\xi dx \quad (5.1)$$

holds.

Unfortunately, we can not answer whether $R\theta - Pu$ is integrable in Lebesgue's sense or not.

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