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\mathbf{Z}_2 Equivariant Cohomology and its Applications to Orthogonal geodesic chords

by

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${\bf Z}_2$ Equivariant Cohomology and Its Application

to Orthogonal Geodesic Chords

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ABSTRACT

A geodesic joining two points of the boundary of a Riemannian manifold is called an *orthogonal geodesic chord* if it intersects with the boundary orthogonally.

Bos' theorem [B] asserts any convex n-disk has n orthogonal geodesic chords. In this case, the involution $\gamma \rightarrow \gamma^{-1} \equiv \gamma(1-\cdot)$ can be considered and equivariant (co)homology of a path space plays essential role. This note gives n such chords for compact contractible manifold instead of the n-disk.

These chords are expected to give periodic solutions on energy surfaces of Hamiltonians of the type "kinetic energy" + "potential".

§1. Introduction.

On any compact energy surface of a Hamiltonian system, we can always find a periodic solution if the Hamiltonian H is a physical one, that is H = T + U = "kinetic energy" + "potential" [H2] [GZ].

Solutions of the Hamiltonian system of given energy e correspond to geodesics with respect to the Jacobi metric

$$ds^2 = (e - U) T.$$

And orthogonal geodesic chords of a compact manifold with boundary, which is diffeomorphic to $\{U \leq e\}$, yields the periodic solution of the Hamiltonian system. Here an orthogonal geodesic chord means a geodesic starting from and ending at a point of the boundary orthogonally.

A partial result has been obtained by Seifert [S] for the case $\{U \leq e\} \approx D^n$, the *n*-disk. In a footnote of the paper, Seifert conjectured that one may have *n* periodic solutions by the method of Lusternik-Schnirelmann [LS]. This problem is still open, although a partial result for the system near the rotationally symmetric one is obtained [H3]. (Remark that this is not the so called "Seifert Conjecture".)

[LS] gives n orthogonal geodesic chords of any convex body in \mathbb{R}^n and Bos [B] extends it to convex n disks.

In this note, we define a number $\nu(M)$, where M is a compact C^{∞} manifold with boundary, and show that there exist at least $\nu(M)$ orthogonal geodesic chords of M if the boundary is convex with respect to the Riemannian metric given on M.

Furthermore we have $\nu(D^n) = n$ and

$$\nu(M) \geq n$$

if M is contractible (n = dim M).

For n = 1 and 2, compact contractible manifold with boundary is always a disk. For n = 3, this question is equivalent to the Poincaré Conjecture. For $n \ge 4$, there are examples of compact contractible manifolds with boundary, which are not homeomorphic to a disk [Ma]. In this case, the boundary is a homology sphere with nontrivial fundamental group.

§2. Numbers determined by compact manifold with boundary.

Let M be a compact C^{∞} manifold with boundary

$$B = \partial M \neq \emptyset$$
.

We define four numbers $\nu(M)$, $\nu_{\pi}(M)$, $\nu_{H}(M)$, and $\nu_{\Pi}(M)$ as follows.

We put $Y_M = \Omega(M; B, B) = \{\omega:[0,1] \to M; \text{ continuous and } \omega(0), \omega(1) \in B\}$ endowed with compact open topology and regard B as a subset of Y_M by the usual way. For simplicity the coefficient field \mathbb{Z}_2 is understood.

(i)
$$\nu_{\pi}(M) = \begin{cases} 1 & \text{if } \pi_{k}(Y_{M}, B) \neq 0 \text{ for some } k \geq 1, \\ 0 & \text{otherwise} \end{cases}$$

(ii)
$$\nu_H(M) = \operatorname{Max} \{ k \geq 0 ; \exists \alpha_1, \alpha_2, \dots, \alpha_{k-1} \in H^*(Y_M) \\ \text{with } \deg \alpha_j > 0, j = 1, \dots, k-1; \exists a \in H_*(Y_M, B) \\ \text{such that } (\alpha_1 \cup \dots \cup \alpha_{k-1}) \cap a \neq 0 \}$$

We remark that

$$(2.1) v_H(M) \ge 1 iff H_*(Y_M, B) \ne 0$$

(iii) Let $\xi: Y_M \to Y_M$ be the involution defined by

$$\xi \omega = \omega^{-1} \equiv \omega(1 - \cdot).$$

$$\nu_{\Pi}(M) = \operatorname{Max} \{ k \geq 0 ; \exists \alpha_{1}, \alpha_{2}, \dots, \alpha_{k-1} \in H_{\Pi}^{*}(Y_{M}), \\
\text{with } \operatorname{deg} \alpha_{j} > 0 \text{ ,and } \exists a \in H_{*}^{\Pi}(Y_{M}, B) \\
\text{such that } (\alpha_{1} \cup \dots \cup \alpha_{k-1}) \cap a \neq 0 \}$$

 H_*^{Π} (H_{Π}^*) means \mathbb{Z}_2 -equivariant (co)homology (see [H1] [N]).

Finally we define a nonnegative integer

(iv)
$$\nu(M) = \text{Max} \{ \nu_{\pi}(M), \nu_{H}(M), \nu_{\Pi}(M) \}$$

Lemma 2 of [H2] gives

$$(2.2) v_{\pi}(M) \ge 1$$

or

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$$(2.3) \nu_H(M) \ge 1 (\iff H_*(Y_M, B) \ne 0),$$

hence we have

$$(2.4) v(M) \geq 1.$$

We also have

Lemma 1. Let L be a closed manifold and N a compact manifold with boundary. Then, if $v_H(N) \ge 1$, we have

$$\nu_H(N \times L) \geq (\text{cup length } L) + \nu_H(N).$$

(proof) Let
$$\alpha_1, \dots, \alpha_{k-1} \in H^*(N)$$
, deg $\alpha_j > 0$ and $a \in H_*(N, \partial N)$ with
$$a' = (\alpha_1 \cup \dots \cup \alpha_{k-1}) \cap a \neq 0.$$

And let $\beta_1, \ldots, \beta_l \in H^*(L)$, deg $\beta_j > 0$, with $\beta' = \beta_1 \cup \cdots \cup \beta_l \neq 0$. We choose $b \in H_*(L)$ so that $<(\beta_1 \cup \cdots \cup \beta_l), b> = 1$, then $\beta' \cap b \neq 0$. Now $a \times b \in H_*((N, \partial N) \times L) = H_*(N \times L, \partial(N \times L))$.

And we have

$$((1\times\beta_1)\cup\cdots\cup(1\times\beta_l)\cup(\alpha_1\times1)\cup\cdots\cup(\alpha_{k-1}\times1)) \cap (a\times b)$$

$$= (1\times\beta')\cap(((\alpha_1\times1)\cup\cdots\cup(\alpha_{k-1}\times1))\cap(a\times b)$$

$$= (1\times\beta')\cap(a'\times b)$$

$$= a'\times(\beta'\cap b)$$

$$\neq 0 \qquad \text{in} \qquad H_*((N\times L), \partial(N\times L)).$$

This proves the lemma. Q.E.D.

§3. Orthogonal Geodesic Chords

First we have

Therem 1. Let M be a compact Riemannian manifold with convex boundary. Then there exist at least v(M) orthogonal geodesic chords of M.

Before giving the proof, we set a path space and distances on it. Let Λ be the set of all p.w. (piecewise) C^{∞} curve $\lambda : [0,1] \to M$ with $\lambda(0)$ and $\lambda(1) \in \partial M$.

For $\lambda_1, \lambda_2 \in \Lambda$, we define

$$d_{\infty}(\lambda_1, \lambda_2) = \max_{0 \le t \le 1} d(\lambda_1(t), \lambda_2(t)),$$

where d is the distance derived from the Riemannian metric on M, and

$$d_1(\lambda_1,\,\lambda_2) = d_{\infty}(\lambda_1,\,\lambda_2) \,+\, (\, \int_0^1 \, (\, |\dot{\lambda_1}(t)| \,-\, |\dot{\lambda_2}(t)| \,)^2 \,\,dt\,\,)^{1/2} \;.$$

Let E be the energy functional $E: \Lambda \to [0, \infty)$ defined by

$$E(\lambda) = \frac{1}{2} \int_0^1 |\dot{\lambda}(t)|^2 dt.$$

E is continuous w.r.t. d_1 (§16 in [Mi]).

Now we have a sequence of continuous mappings

$$(\Lambda, d_1) \stackrel{i}{\subset} (\Lambda, d_{\infty}) \stackrel{j}{\subset} (Y_M, d_{\infty}) .$$

We remark that these i and j both give homotopy equivalences by Theorem 17.1 in [Mi].

For $K \ge 0$, we put

$$\Lambda^K = \{ \lambda \in \Lambda ; E(\lambda) \le K \} .$$

Then Lemma A.1.4 in [K], slightly changed so as to suit for our situation, that is, with convex boundary, gives

Lemma 2. We take the distance d_{∞} on Λ . For given $K \geq 0$, there is a deformation (continuous map)

$$\mathscr{D}:\Lambda^K\times [0,1]\to \Lambda^K$$

satisfying

- (i) $\mathscr{Q}(\cdot, 0) = i_d : \Lambda^K \to \Lambda^K$
- (ii) W is E decreasing, that is

$$E(\mathcal{D}(\lambda, t)) \leq E(\mathcal{D}(\lambda, s))$$
 if $t \geq s$

- (iii) $\mathfrak{D}(\lambda, 1) = \lambda$ if and only if λ is an orthogonal geodesic chord (or constant curve on $B = \partial M$).
- (iv) Let $0 < \kappa < K$ and C_{κ} be the set of all orthogonal geodesic chords of Energy κ . Then for any open neighborhood W of C_{κ} (one may choose $W = \emptyset$ in the case $C_{\kappa} = \emptyset$), there exists $\rho >$) such that

$$\mathcal{D} \Lambda^{\kappa+\rho} \subset W \cup \Lambda^{\kappa-\rho}$$

where $\mathfrak{D} = \mathfrak{D}(\cdot, 1) : \Lambda^K \to \Lambda^K$.

(v) $\mathfrak{D}(\cdot, t) : \Lambda^K \to \Lambda^K$ is equivariant for any $t \in [0, 1]$.

This lemma means that the convexity of the boundary plays the role of the condition (C) of Palais-Smale.

(Proof of Theorem 1)

First we prove $\nu_{\pi}(M) = 1$ gives at least one non-constant orthogonal geodesic chord.

As usual there is an $\epsilon > 0$ with

$$\pi_k(\Lambda, \Lambda^{\epsilon}) \cong \pi_k(\Lambda, \Lambda^0) \cong \pi_k(Y_M, B)$$

(see the remark above). Let a be the non-trivial element of $\pi_k(\Lambda, \Lambda^{\epsilon})$. We put

$$\kappa_a = \inf_{f \in a} \sup E(f(D^k)) .$$

Although E is not continuous w.r.t. d_x , this is finite because

$$i:(\Lambda,d_1)\subset(\Lambda,d_x)$$

is a homotopy equivalence. As usual Lemma 2, in particular (iv), gives that κ_a is a critical value of E, that is, $C_{\kappa_a} \neq \emptyset$, and $\kappa_a \geq \epsilon$ by the fact that a is non-trivial in the relative homotopy $\pi_k(\Lambda, \Lambda^{\epsilon})$.

The case $\nu_H(M)$ is also the usual one.

Now consider the equivariant case.

We put $\Lambda_{\Pi} \equiv S^{\infty} \times \Lambda$, the orbit space of $S^{\infty} \times \Lambda$ under the involution $(\zeta, \lambda) \mapsto (-\zeta, \xi \lambda)$.

Since E is invariant under ξ , we can define

$$\tilde{E}:\Lambda_{\Pi}\rightarrow [0,\infty)$$

by $\tilde{E}[\zeta, \lambda] = E(\lambda)$, where $[\zeta, \lambda]$ is the equivalence class represented by (ζ, λ) .

Let a be the nontrivial element of $H_*^{\Pi}(\Lambda, \Lambda^{\epsilon}) = H_*(\Lambda_{\Pi}, \Lambda_{\Pi}^{\epsilon})$. We put

$$\tilde{\kappa_a} = \inf_{z \in a} \tilde{E}(|z|)$$

where $|z|=\bigcup_i {
m Im} \ \sigma_i$, $z=\sum_i \sigma_i$, $\sigma_i:\Delta_q-\Lambda_\Pi$, singular simplex.

Then, by Lemma 2 in [H3], $C_{\kappa_a} \neq \emptyset$ and $\kappa_a \geq \epsilon$.

Furthermore, assume that there exists $\alpha \in H^*(\Lambda_{\Pi})$ with $\deg \alpha > 0$, such that $b = \alpha \cap a \neq 0$ in $H_*(\Lambda_{\Pi}, \Lambda_{\Pi}^{\epsilon})$. Then $\tilde{\kappa_b}$ is also a critical value with $\tilde{\kappa_b} \geq \epsilon$.

In this case, in general, $\vec{\kappa_b} \leq \vec{\kappa_a}$ and if $\vec{\kappa_b} = \vec{\kappa_a}$, then there are infinitely many critical points on the level (a version of Lemma 2 in [H3]).

Remarking that

$$\alpha_1 \cap (\alpha_2 \cap a) = (\alpha_1 \cup \alpha_2) \cap a$$
,

we have at least $\nu_{\parallel}(M)$ critical points with $\geq \epsilon$ (non-constant orthogonal geodesic chords). Q.E.D.

So (2.4) gives

Corollary. Any compact Riemannian manifold with convex boundary has an orthogonal geodesic chord.

This is Theorem C of [GZ].

[GZ] also gives another proof for Bos' theorem. There is an example of compact Riemannian manifold with boundary with no orthogonal geodesic chords[B], hence the assumption of convex boundary is necessary.

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Since we have

$$(3.1) v(D^n) = n$$

(the proof is given later), Theorem 1 also gives Bos' theorem.

Now we have

Theorem 2. Let M be a compact contractible manifold with convex boundary. Then there exist dim M orthogonal geodesic chords of M.

In this case we shall show

$$(3.2) v_{\Pi}(M) \geq \dim M,$$

giving Theorem 2 using Theorem 1.

To prove Theorem 2, we prepare the following

Lemma 3. Let B be a closed manifold of dimension n. Put $B^2 = B \times B$ and define the involution $\xi: B^2 \to B^2$ by

$$\xi(x,y)=(y,x).$$

Then there exist $a \in H_{2n}^{\Pi}(B^2, \Delta)$ and $\theta \in H_{\Pi}^1(B)$ with $\theta^n \cap a \neq 0$ in $H_n^{\Pi}(B^2, \Delta)$, where Δ denotes the diagonal set.

(Proof) This is Theorem 2 of [H1], which needs the work by Steenrod [N]. Q.E.D.

(Proof of Theorem 2)

We put $B = \partial M$. Let

$$\pi: Y_M \to B^2$$

be the projection defined by

$$\omega \rightarrow (\omega(0), \omega(1)).$$

Since the mapping

$$\pi': S^{\infty} \times Y_M \rightarrow S^{\infty} \times B^2$$

defined by

$$(\zeta, \omega) \rightarrow (\zeta, \pi(\omega))$$

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is equivariant, we have the mapping

$$\tilde{\pi}: S^{\infty} \underset{\Pi}{\times} Y_{M} \to S^{\infty} \underset{\Pi}{\times} B^{2}.$$

It is easy to see that $\tilde{\pi}$ gives a fibre space.

We fix base points $b \in B$ and $* \in S^{\infty}$ and take

$$\tilde{*} = [*, (b, b)]$$

as the base point of $S^{\infty} \underset{\Pi}{\times} B^2$. Then we can identify the fibre $\tilde{\pi}^{-1}(\tilde{*})$ and ΩM . Thus we have a fibration

$$\Omega M \to S^{\times}_{\Pi} Y_{M} \stackrel{\hat{\pi}}{\to} S^{\times}_{\Pi} B^{2}.$$

Until we obtain the fibration (3.3), we don't use the assumption that M is contractible.

Now, since $M \simeq b$, we have $\Omega M \simeq b$. Hence the spectral sequence of the (co)homology of the fibration is a very simple one and we can easily have the conclusion

$$\nu_{\Pi}(M) \geq \dim B + 1 = \dim M$$

using Lemma 3.

This is (3.2), giving the theorem. Q.E.D.

§4. Open Problems.

In this section, we propose some open problems.

Let M be a compact manifold with boundary.

(i)
$$\nu_H(M) \geq 1$$
?

Although this gives only one orthogonal geodesic chord by Lemma 2 and it is already obtained from (2.2), there is a little meaning because it appears in the assumption of Lemma 1.

(ii)
$$\nu_{\Pi}(M) \geq \nu_{H}(M)$$
?

For the case $M = D^n$, we have

$$(4.1) v_{\Pi}(D^n) = n.$$

In fact (3.2) gives $\nu_{\Pi}(D^n) \ge n$. And if $\nu_{\Pi}(D^n) > n$, we have always n+1 orthogonal geodesic chords. But for the solid ellipsoid whose lengths of axes are all different, we have exactly n orthogonal geodesic chords if the Riemannian metric considered is the standard one.

One can easily obtain $\nu_H(D^n) = 2$, hence in this case we have (ii).

This corresponds to the fact that

$$\operatorname{cup length} S^{n-1} = 1$$

but

$$\operatorname{cup length} \mathbf{R} P^{n-1} = n-1,$$

showing the importance of \mathbb{Z}_2 -action, in particular, \mathbb{Z}_2 -equivariant cohomology under an involution.

(iii) Study the structure of $H_{\Pi}^*(Y_M)$.

For contractible M, this is isomorphic to $H_{\Pi}^*(\partial M \times \partial M)$, which is completely determined by the Isomorphism Theorem by Steenrod [N]. For general M, it seems to be difficult to determine the equivariant cohomology, but this is indispensable in order to count $\nu_{\Pi}(M)$.

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