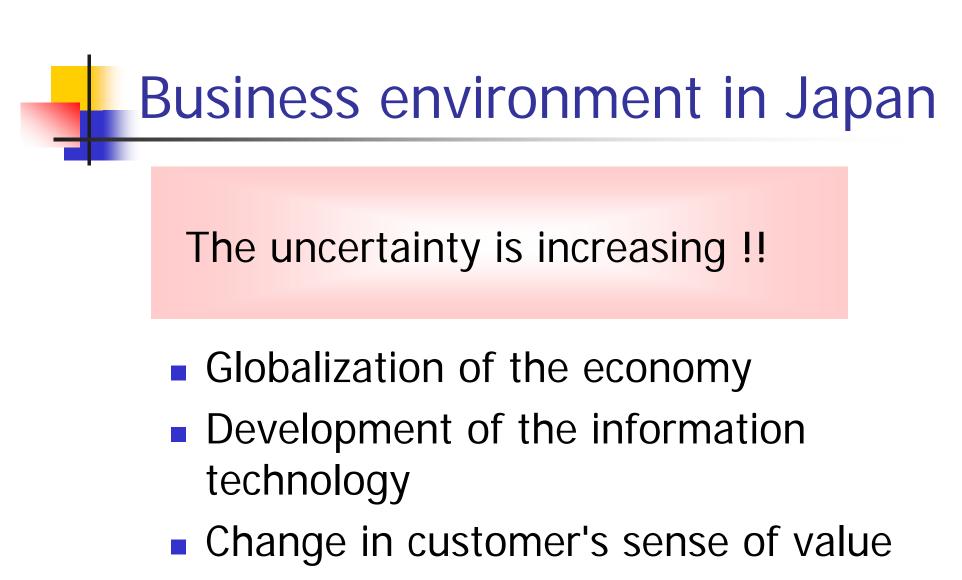
Measuring the Effectiveness of Marketing Activities and Baseline Sales from POS Data using Bayesian State Space Models

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Deregulation

Main aim

- To develop the methodology for predicting daily and baseline sales of individual items by considering specific factors
- The prediction is very useful for
 - inventory management
 - marketing strategy planning
 - manpower planning
 - production planning

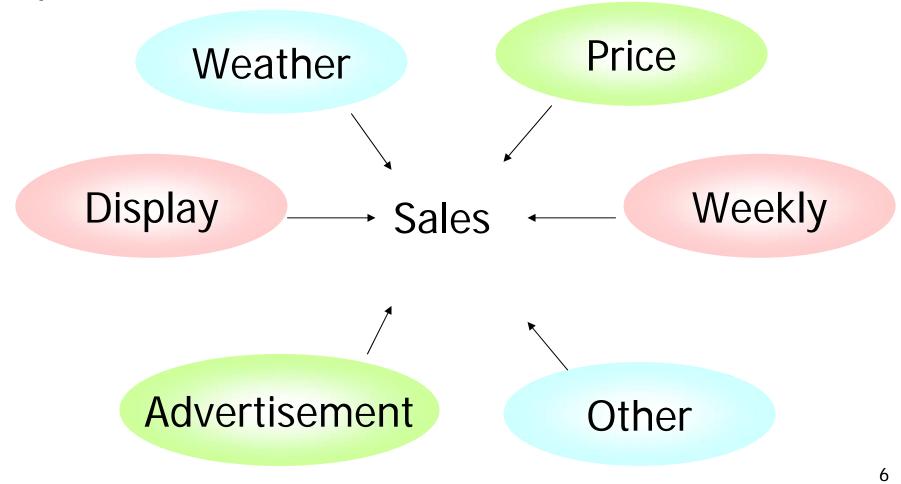
Agenda

- Data description
- Model description
- Bayesian MCMC Estimation
- Model evaluation
- Application results
- Conclusion

Data description

- Daily unit sales for 10 foods
 - Cold beverages
 - Coffee
 - Tea beverages
 - Cup noodle
 - Rice balls
 - Sandwiches
 - Packed lunches
 - Jelly
 - Yogurt

Data description



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Model description

Bayesian MCMC Estimation

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- A general state space model (Kitagawa, 1987) enables us to conduct flexible time series modeling.
- Observation model

$$y_t \sim f(y_t | F_t, h_t, ..., h_1)$$

System model

$$h_t \sim f(h_t | F_t, h_{t-1}, ..., h_1)$$

Observation model

Daily unit of sales

- = Baseline sales
- + Sales affected by environmental effect
- + Sales obtained from marketing promotion

Observation model (Poisson model) Daily unit sales

 $\mathbf{\dot{y}}_{t} \sim Poisson(\lambda_{t} | \mathbf{x}_{t})$ $\mathbf{x}_{t} = (w_{t}, r_{t}, p_{t}, d_{t}, a_{t})'$ $\lambda_{t} = h_{t} + \beta_{1}w_{t} + \beta_{2}r_{t} + \beta_{3}p_{t} + \beta_{4}d_{t} + \beta_{5}a_{t}$ Baseline unit sales Weather effect Price promotion effect

Weekly effect Display promotion effect Advertisement effect

System model (q-th order trend model)

$$\Delta^q h_t = \varepsilon_t \qquad \varepsilon_t \sim N(0, \sigma^2)$$

Example

$$(q = 1): h_{t} = h_{t-1} + \varepsilon_{t}$$
$$(q = 2): h_{t} = 2h_{t-1} - h_{t-2} + \varepsilon_{t}$$

Each of the 10 foods follow the Poisson model.

$$y_{jt} \sim Poisson(\lambda_{jt} | \mathbf{x}_{jt}), \ j = 1,...,10$$

We consider that the daily unit sales are mutually dependent on each other.

$$\begin{cases} \Delta^{q} h_{jt} = \varepsilon_{jt}, \ \varepsilon_{jt} \sim N(0, \sigma_{j}^{2}), \ j = 1, ..., 10 \\ Cov(\varepsilon_{j,t}, \varepsilon_{k,t}) = \sigma_{jk} \end{cases}$$

Summarizing the above specification leads to the following observation equation and the system equation:

Observation equation

$$y_{jt} \sim f(y_{jt} | h_{jt}; \mathbf{x}_{jt}, \boldsymbol{\beta}_{j})$$

System equation

$$\mathbf{h}_{t} \sim f(\mathbf{h}_{t} | \mathbf{h}_{t-1}, ..., \mathbf{h}_{t-q}, \Sigma), \Sigma = (\sigma_{ij})$$

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Bayesian estimation via Markov chain Monte Carlo (1/2)

- A set of n independent observations
- Likelihood function

$$L(D_{n}|\boldsymbol{\theta}, X_{n}) = \prod_{t=1}^{n} f(\boldsymbol{y}_{t}|F_{t-1}, \boldsymbol{x}_{t}, \boldsymbol{\theta})$$

$$= \prod_{t=1}^{n} \left[\prod_{j=1}^{p} f(y_{jt}|F_{t-1}, \boldsymbol{x}_{jt}, \boldsymbol{\theta}) \right]$$

$$= \prod_{t=1}^{n} \left[\prod_{j=1}^{p} \int f(y_{jt}|h_{jt}; \boldsymbol{x}_{jt}, \boldsymbol{\beta}) f(\boldsymbol{h}_{t}|\boldsymbol{h}_{t-1}, ..., \boldsymbol{h}_{t-q}; \boldsymbol{\Sigma}) d\boldsymbol{h}_{t} \right]$$

Observation model System model 16

Bayesian estimation via Markov chain Monte Carlo (2/2)

 Markov chain Monte Carlo considers the state vector as model parameters

 $\mathbf{h} = (\mathbf{h}_1, \mathbf{h}_2, \dots, \mathbf{h}_n)$

A posterior distribution

$$\pi(\boldsymbol{\theta}, \boldsymbol{h} | D_n, X_n) \propto \pi(\boldsymbol{\theta})$$

$$\times \prod_{t=1}^n \prod_{t=1}^n f(y_{jt} | h_{jt}; \boldsymbol{x}_{jt}, \boldsymbol{\beta}) f(\boldsymbol{h}_t | \boldsymbol{h}_{t-1}, ..., \boldsymbol{h}_{t-q}; \Sigma).$$

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Maximisation of the posterior mean of the expected likelihood

 Ando (2006) considered the maximization of the posterior mean of the expected loglikelihood (PMELL):

$$\eta = E_{Z_n} \left[E_{\boldsymbol{\theta}|D_n, X_n} [\log L(Z_n | \boldsymbol{\theta}, X_n)] \right]$$
$$= \int \left[\int \log L(Z_n | \boldsymbol{\theta}, X_n) \pi(\boldsymbol{\theta} | D_n, X_n) d\boldsymbol{\theta} \right] dG(Z_n | X_n),$$

• The best model is chosen by maximising η .

Ando (2006)

The asymptotic bias is

$$n\hat{b} \approx E_{\boldsymbol{\theta}|D_n, X_n} [\log\{L(D_n|\boldsymbol{\theta}, X_n)\pi(\boldsymbol{\theta})\}] + \dim\{\boldsymbol{\theta}\}/2$$
$$-\log\{L(D_n|\hat{\boldsymbol{\theta}}_n, X_n)\pi(\hat{\boldsymbol{\theta}}_n)\} + \operatorname{tr}\left\{J_n^{-1}(\hat{\boldsymbol{\theta}}_n)I_n(\hat{\boldsymbol{\theta}}_n)\right\},$$

where

$$I_{n}(\boldsymbol{\theta}) = \frac{1}{n} \sum_{t=1}^{n} \left\{ \frac{\partial \eta_{n}(\boldsymbol{y}_{t}, \boldsymbol{\theta})}{\partial \boldsymbol{\theta}} \frac{\partial \eta_{n}(\boldsymbol{y}_{t}, \boldsymbol{\theta})}{\partial \boldsymbol{\theta}'} \right\},$$

$$J_{n}(\boldsymbol{\theta}) = -\frac{1}{n} \sum_{t=1}^{n} \left\{ \frac{\partial^{2} \eta_{n}(\boldsymbol{y}_{t}, \boldsymbol{\theta})}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}'} \right\},$$

with $\eta_n(\boldsymbol{y}_t, \boldsymbol{\theta}) = \log f(\boldsymbol{y}_t | F_{t-1}, \boldsymbol{x}_t, \boldsymbol{\theta}) + \log \pi(\boldsymbol{\theta})/n.$ 20

Ando (2006)

- The prior is dominated by the likelihood as the sample size becomes large.
- The specified parametric models contain the true model or are close to the true model



Bayesian predictive information criterion

 Bayesian predictive information criterion (BPIC Ando (2006)):

BPIC =
$$-2E_{\theta|D_n,X_n} \left[\log L(D_n | \theta, X_n) \right] + 2\dim\{\theta\}$$

 We choose the predictive distribution that minimises the BPIC score.

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Application results

The posterior mean of the log-likelihood and BPIC scores for each of q-th order trend models.

q	1	2	3	4
$\hat{\eta}$	-1543.081	-1507.530	-1492.693	-1483.921
BPIC	3296.162	3245.060	3235.386	3237.842
CPU time	16.75	17.54	18.28	19.09

 The CPU time (seconds) to generate 100 iterations is also reported.

Observation model

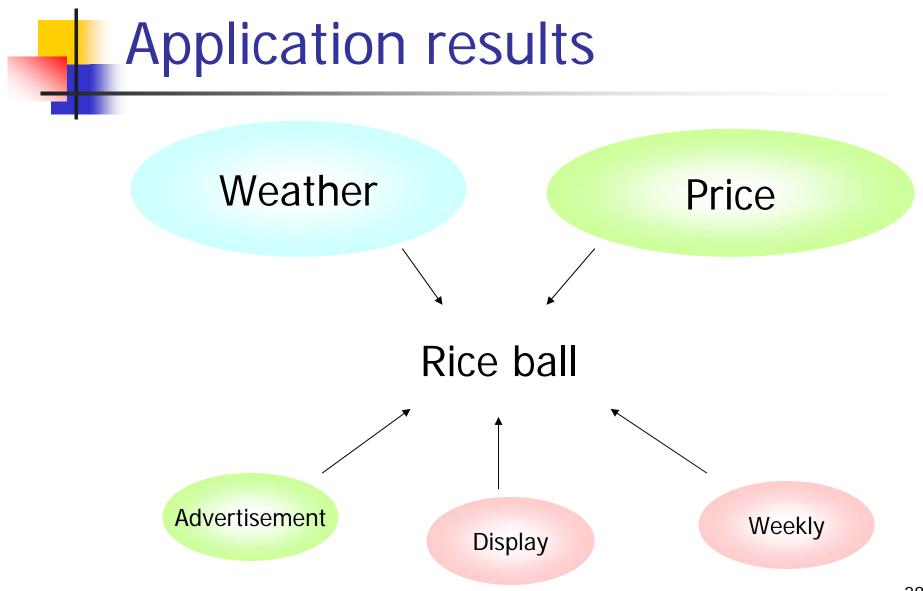
 $y_{t} \sim Poisson(\lambda_{t} | \mathbf{x}_{t})$ $\mathbf{x}_{t} = (w_{t}, r_{t}, p_{t}, d_{t}, a_{t})'$ $\lambda_{t} = h_{t} + \beta_{1}w_{t} + \beta_{2}r_{t} + \beta_{3}p_{t} + \beta_{4}d_{t} + \beta_{5}a_{t}$ Baseline unit sales Weather effect Price promotion effect
Weekly effect Display promotion effect Advertisement effects

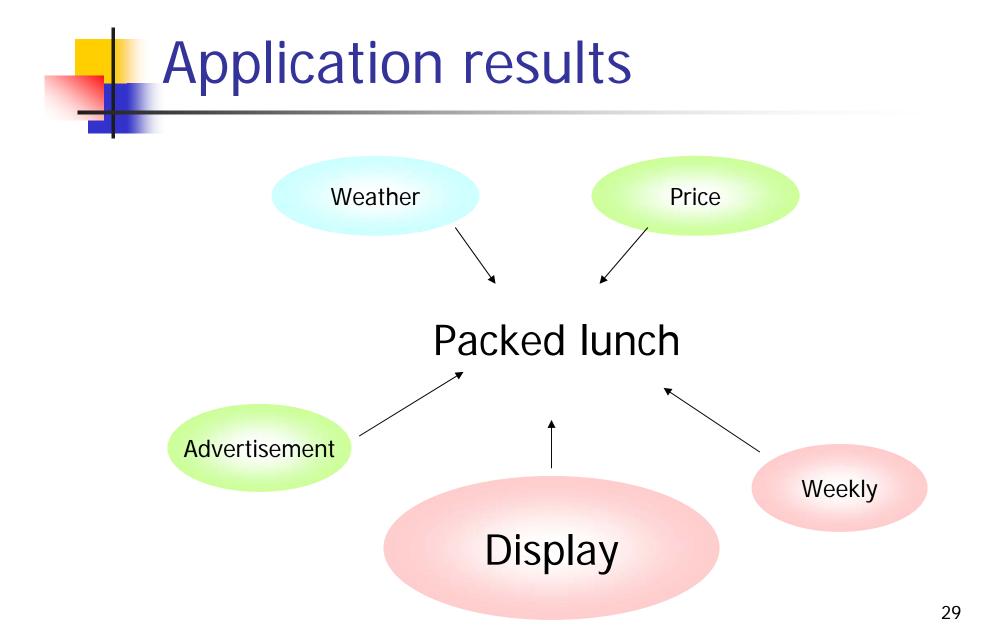
_			PMs	95	5% CIs			PMs	PMs 95	
(CB	β_{11}	0.66	[0.14	1.18]	SA	β_{61}	0.52	[0.06	0.97]
		β_{12}	7.52	[6.52	8.59]		β_{62}	0.22	[0.02	0.60]
		β_{13}	41.2	[40.2	42.3]		β_{63}	1.53	[0.17	2.56]
		β_{14}	6.38	[5.71	7.16]		eta_{64}	2.36	[1.85	2.71]
		β_{15}	1.37	[0.09	2.47]		β_{65}	0.64	[0.04	1.59]
_	CF	β_{21}	0.58	[0.15	1.06]	P1	β_{71}	0.52	[0.07	1.28]
- 1		β_{22}	13.2	[12.4	13.8]		β_{72}	0.99	[0.13	1.51]
		β_{23}	19.9	[19.3	20.6]		β_{73}	3.06	[1.04	4.21]
		β_{24}	4.82	[3.97	6.19]		β_{74}	17.0	[16.2	17.8]
		β_{25}	1.81	[1.10	2.68]		β_{75}	1.64	[0.98	2.40]
'	ТВ	β_{31}	0.63	[0.05	1.67]	P2	β_{81}	0.29	[0.04	0.64]
		β_{32}	9.67	[8.60	10.5]		β_{82}	0.71	[0.03	1.33]
		β_{33}	1.03	[0.21	1.59]		β_{83}	104.57	[103.6	105.4]
		β_{34}	3.15	[2.44	3.70]		β_{84}	0.45	[0.03	1.45]
		β_{35}	11.2	[10.4	12.2]		β_{85}	0.38	[0.04	0.84]
(CN	β_{41}	1.01	[0.06	1.97]	JE	β_{91}	5.65	[4.47	6.89]
		β_{42}	4.61	[3.95	5.24]		β_{92}	5.65	[4.06	6.56]
		β_{43}	1.66	[1.01	2.17]		β_{93}	0.55	[0.08	1.15]
		β_{44}	9.47	[8.50	11.0]		β_{94}	49.3	[48.4	51.3]
		β_{45}	2.68	[1.27	4.12]		β_{95}	36.3	[35.0	37.8]
]	RB	β_{51}	1.70	[0.30	2.68]	YO	β_{101}	1.52	[0.78	2.13]
		β_{52}	16.5	[15.4	17.3]		β_{102}	14.6	[14.1	15.1]
		β_{53}	3.23	[2.60	3.88]		β_{103}	0.36	[0.04	0.84]
		β_{54}	13.1	[12.5	13.7]		β_{104}	13.5	[11.7	14.9]
_		β_{55}	0.95	[0.50	1.69]		β_{105}	26.2	[25.7	26.9]

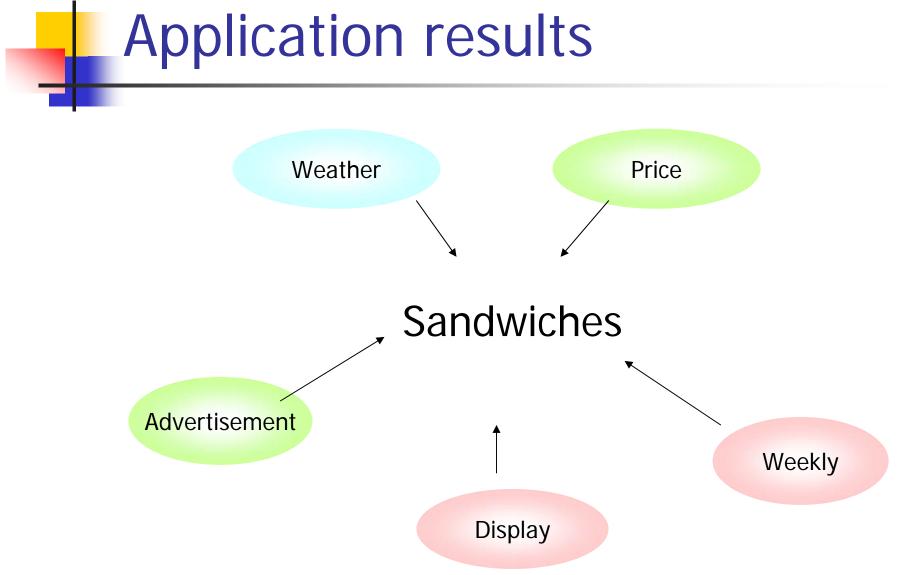
Application results

Observation model

 $y_t \sim Poisson(\lambda_t | \mathbf{x}_t)$ $\mathbf{X}_{t} = (w_{t}, r_{t}, p_{t}, d_{t}, a_{t})'$ $\lambda_t = h_t + 1.7 w_t + 16.5 r_t + 3.2 p_t + 13.1 d_t + 0.95 a_t$ Baseline unit sales Weather effect Price promotion effect Weekly effect Display promotion effect Advertisement effect







Each of the 10 foods follow the Poisson model.

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We consider that the daily unit sales are mutually dependent on each other.

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Application results

The posterior means of correlation

	CB	CF	TB	CN	RB	SA	P1	P2	JE	YO
CB:	1.00	0.54	0.35	0.15	0.52	0.18	0.17	0.24	0.35	0.46
CF:	0.54	1.00	0.37	0.29	0.40	0.21	0.36	0.12	0.49	0.44
TB:	0.35	0.37	1.00	0.55	0.74	0.13	0.34	0.34	0.28	0.36
CN:	0.15	0.29	0.55	1.00	0.47	0.23	0.28	0.17	0.41	0.29
RB:	0.52	0.40	0.74	0.47	1.00	0.07	0.31	0.35	0.59	0.61
SA:	0.18	0.21	0.13	0.23	0.07	1.00	0.43	0.34	0.22	0.23
P1:	0.17	0.36	0.34	0.28	0.31	0.43	1.00	-0.24	0.41	0.61
P2:	0.24	0.12	0.34	0.17	0.35	0.34	-0.24	1.00	0.20	0.13
JE:	0.35	0.49	0.28	0.41	0.59	0.22	0.41	0.20	1.00	0.83
YO:	0.46	0.44	0.36	0.29	0.61	0.23	0.61	0.13	0.83	1.00

CB: cold beverages, CF: coffee, TB: tea beverages, CN: cup noodle, RB: rice balls, SA: sandwiches, P1: packed lunches (type1), P2: packed lunches (type2), JE: jelly and YO: yogurt. 32

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Conclusion

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- The problem of identifying unobserved baseline sales, marketing promotion effects and other specific effects using POS data is considered.
- General state space model
- Bayesian MCMC estimation
- Bayesian predictive information criterion is utilized.
- The unobserved baseline sales, marketing promotion effects and other specific effects are estimated simultaneously.



Thank you for your attention